

# From words to features to trees: Computing a world tree of languages from word lists

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35th European Summer School in Logic, Language and Information

*August 7, 2024*



WORDS BONES GENES TOOLS  
Tracking Linguistic, Cultural, and Biological Trajectories of the Human Past

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# Typological distributions

- common practice since Greenberg (1963):
  - collect a sample of languages
  - classify them according to some typological feature
  - ⇒ skewed distribution indicates something interesting going on
- Problem: languages are not independent samples
- skewed distribution may reflect
  - skewed diversification rate across families
  - properties of an ancestral bottleneck
- balanced sampling mitigates the first, but not the second problem

# Typological distributions

Maslova (2000):

*"If the A-distribution for a given typology cannot be assumed to be stationary, a distributional universal cannot be discovered on the basis of purely synchronic statistical data."*

*"In this case, the only way to discover a distributional universal is to **estimate transition probabilities** and as it were to 'predict' the stationary distribution on the basis of the equations in (1)."*



# Defining models

- feature values evolve according to a *continuous time Markov chain* (CTMC)
- evolution along a phylogeny
- phylogenetic tree is only partially known - represented here as posterior distribution of Bayesian phylogenetic inference from lexical data (from ASJP)

# Discrete time Markov chains

Ewens and Grant (2005), 4.5–4.9, 11

## Definition

A *discrete time Markov chain* over a countable state space  $S$  is a function from  $\mathbb{N}$  into random variables  $X$  over  $S$  with the *Markov property*

$$\mathbb{P}(X_{n+1} = x | X_1 = x_1, X_2 = x_2, \dots, X_n = x_n) = \mathbb{P}(X_{n+1} = x | X_n = x_n)$$

which is *stationary*:

$$\forall m, n : \mathbb{P}(X_{n+1} = x_i | X_n = x_j) = \mathbb{P}(X_{m+1} = x_i | X_m = x_j)$$

# Discrete time Markov chains

A dt Markov chain with finite state space is characterized by

- its *initial distribution*  $X_0$ , and
- its *transition Matrix*  $P$ , where

$$p_{ij} = \mathbb{P}(X_{n+1} = x_j | X_n = x_i)$$

$P$  is a *stochastic matrix*, i.e.  $\forall i \sum_j p_{i,j} = 1$ .

## Definition

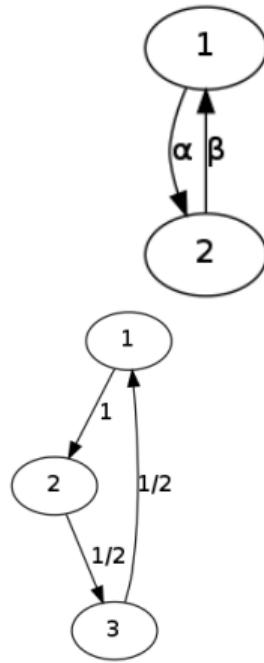
“ $\text{Markov}(\lambda, P)$ ” is the dt Markov chain with initial distribution  $\lambda$  and transition matrix  $P$ .

# Discrete time Markov chains

Transition matrices over a finite state space can conveniently be represented as weighted graphs.

$$P = \begin{pmatrix} 1 - \alpha, \alpha \\ \beta, 1 - \beta \end{pmatrix}$$

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1/2 & 1/2 \\ 1/2 & 0 & 1/2 \end{pmatrix}$$



# Discrete time Markov chains

- We say  $i \rightarrow j$  if there is a path (with positive probabilities in each step) from  $x_i$  to  $x_j$ .
- The symmetric closure of this relation,  $i \leftrightarrow j$ , is an equivalence relation. It partitions a Markov chain into *communicating classes*.
- A Markov chain is *irreducible* iff it consists of a single communicating class.
- A state  $x_i$  is *recurrent* iff

$$\forall n \exists m : \mathbb{P}(X_{n+m} = x_i) > 0$$

- A state is *transient* iff it is not recurrent.

# Discrete time Markov chains

- For each communicating class  $C$ : Either all of its states are transient or all of its states are recurrent.

# Discrete time Markov chains

By convention, we assume that  $\lambda$  is a row vector. The distribution at time  $n$  is given by

$$\mathbb{P}(X_t = x_i) = (\lambda P^n)_i$$

# Discrete time Markov chains

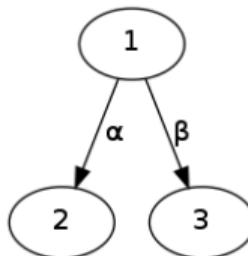
For each stochastic matrix  $P$  there is at least one distribution  $\pi$  with

$$\pi P = P$$

( $\pi$  is a left eigenvector for  $P$ .)  $\pi$  is called an **invariant distribution**.

$\pi$  need not be unique:

$$P = \begin{pmatrix} 1 - \alpha - \beta & \alpha & \beta \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



$\pi = (\gamma, \delta, \delta)$  is a left eigenvector for  $P$  for each  $\gamma, \delta \in [0, 1]$ .

# Discrete time Markov chains

If an irreducible Markov chain converges, then it converges to an invariant distribution:

If  $\lim_{n \rightarrow \infty} P^n = A$ , then

- there is a distribution  $\pi$  with  $A_i = \pi$  for all  $i$ , and
- $\pi$  is invariant.

$\pi$  is called the **equilibrium distribution**. Not every Markov chain has an equilibrium:

$$P = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

# Discrete time Markov chains

## Definition

- The **period**  $k$  of state  $x_i$  is defined as

$$k = \gcd\{n : \mathbb{P}(X_n = i | X_0 = i) > 0\}$$

- A state is **aperiodic** iff its period = 1.
- A Markov chain is **aperiodic** iff each of its states is aperiodic.

## Theorem

If a finite Markov chain is irreducible and aperiodic, then

- it has exactly one invariant distribution,  $\pi$ , and
- $\pi$  is its equilibrium.

# Discrete time Markov chains

## Theorem

If a finite Markov chain is irreducible and aperiodic, with equilibrium distribution  $\pi$ , then

$$\lim_{n \rightarrow \infty} \frac{|\{k < n | X_k = x_i\}|}{n} = \pi_i$$

Intuitively: the relative frequency of times spent in a state converges to the equilibrium probability of that state.

# Continuous time Markov chains

- If  $P$  is the transition matrix of a discrete time Markov process, then so is  $P^n$ .
- In other words,  $P^n$  give the transition probabilities for a time interval  $n$ .
- Generalization:
  - $P(t)$  is transition matrix as a function of time  $t$ .
  - For discrete time:  $P(t) = P(1)^t$ .
  - How can this be generalized to continuous time?

# Matrix exponentials

## Definition

$$e^A \doteq \sum_{k=0}^{\infty} \frac{A^k}{k!}$$

Some properties:

- $e^0 = I$
- If  $AB = BA$ , then  $e^{A+B} = e^A e^B$
- $e^{nA} = (e^A)^n$
- If  $Y$  is invertible, then  $e^{YAY^{-1}} = Ye^AY^{-1}$
- $e^{\text{diag}(x_1, \dots, x_n)} = \text{diag}(e^{x_1}, \dots, e^{x_n})$

# Continuous time Markov chains

## Definition (Q-matrix)

A square matrix  $Q$  is a **Q-matrix** or **rate matrix** iff

- $q_{ii} \leq 0$  for all  $i$ ,
- $q_{ij} \geq 0$  iff  $i \neq j$ , and
- $\sum_j q_{ij} = 0$  for all  $i$ .

## Theorem

If  $P$  is a stochastic matrix, then there is exactly one Q-matrix  $Q$  with

$$e^Q = P.$$

# Continuous time Markov chains

## Definition

Let  $Q$  be a Q-matrix and  $\lambda$  the initial probability distribution. Then

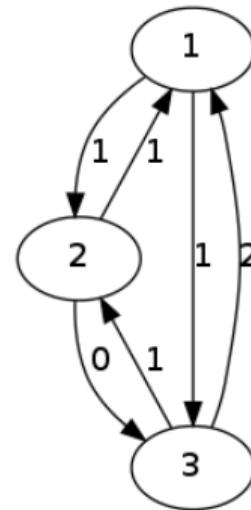
$$X(t) \doteq \lambda e^{tQ}$$

is a **continuous time Markov chain**.

# Continuous time Markov chains

Q-matrices can be represented as graphs in the straightforward way (with loops being omitted).

$$Q = \begin{pmatrix} -2 & 1 & 1 \\ 1 & -1 & 0 \\ 2 & 1 & -3 \end{pmatrix}$$



# Description in terms of jump chain/holding times

Let  $Q$  be a Q-matrix. The corresponding **jump matrix**  $\Pi$  is defined as

$$\pi_{ij} = \begin{cases} -q_{ij}/q_{ii} & \text{if } j \neq i \text{ and } q_{ii} \neq 0 \\ 0 & \text{if } j \neq i \text{ and } q_{ii} = 0 \end{cases}$$

$$\pi_{ii} = \begin{cases} 0 & \text{if } q_{ii} \neq 0 \\ 1 & \text{if } q_{ii} = 0 \end{cases}$$

$$Q = \begin{pmatrix} -2 & 1 & 1 \\ 1 & -1 & 0 \\ 2 & 1 & -3 \end{pmatrix} \quad \Pi = \begin{pmatrix} 0 & 1/2 & 1/2 \\ 1 & 0 & 0 \\ 2/3 & 1/3 & 0 \end{pmatrix}$$

# Description in terms of jump chain/holding times

Let  $Q$  be a Q-matrix and  $\Pi$  the corresponding jump matrix. The Markov process described by  $\langle \lambda, Q \rangle$  can be conceived as:

- ① Choose an initial state according to distribution  $\lambda$ .
- ② If in state  $i$ , wait a time  $t$  that is exponentially distributed with parameter  $-q_{ii}$ .
- ③ Then jump into a new state  $j$  chosen according to the distribution  $\Pi_{i\cdot}$ .
- ④ Goto 2.

# Continuous time Markov chains

Let  $M = \langle \lambda, Q \rangle$  be a continuous time Markov chain and  $\Pi$  be the corresponding jump matrix.

- A state is recurrent (transient) for  $M$  if it is recurrent (transient) for a discrete time Markov chain with transition matrix  $\Pi$ .
- The communicating classes of  $M$  are those defined by  $\Pi$ .
- $M$  is irreducible iff  $\Pi$  is irreducible.

# Continuous time Markov chains

## Theorem

If  $Q$  is irreducible and recurrent. Then there is a unique distribution  $\pi$  with

- $\pi Q = 0$
- $\pi e^{tQ} = \pi$
- $\lim_{t \rightarrow \infty} (e^{tQ})_{ij} = \pi_j$

# Time reversibility

- Does **not** mean that  $a \rightarrow b$  and  $b \rightarrow a$  are equally likely.
- Rather, the condition is

$$\begin{aligned}\pi_a p(t)_{ab} &= \pi_b p(t)_{ba} \\ \pi_a q_{ab} &= \pi_b q_{ba}\end{aligned}$$

- This means that sampling an  $a$  from the equilibrium distribution and observe a mutation to  $b$  in some interval  $t$  is as likely as sampling a  $b$  in equilibrium and see it mutate into  $a$  after time  $t$ .

# Two-states model, equal rates

$$Q = \begin{pmatrix} -r & r \\ r & -r \end{pmatrix} \quad P(t) = \frac{1}{2} \begin{pmatrix} 1 + e^{-2rt} & 1 - e^{-2rt} \\ 1 - e^{-2rt} & 1 + e^{-2rt} \end{pmatrix}$$

$$\pi = (1/2, 1/2)$$

# Two-states model, different rates

$$Q = \begin{pmatrix} -r & r \\ s & -s \end{pmatrix} \quad P(t) = \frac{1}{r+s} \begin{pmatrix} s + re^{-(r+s)t} & r - re^{-(r+s)t} \\ s - se^{-(r+s)t} & r + se^{-(r+s)t} \end{pmatrix}$$

$$\pi = (s/r+s, r/r+s)$$

## Two-states model, different rates

- if we measure time in expected number of mutations, we have

$$r + s = 1$$

- therefore:

### Two-state model

$$Q = \begin{pmatrix} -r & r \\ s & -s \end{pmatrix} \quad P(t) = \begin{pmatrix} s + re^{-t} & r - re^{-t} \\ s - se^{-t} & r + se^{-t} \end{pmatrix}$$

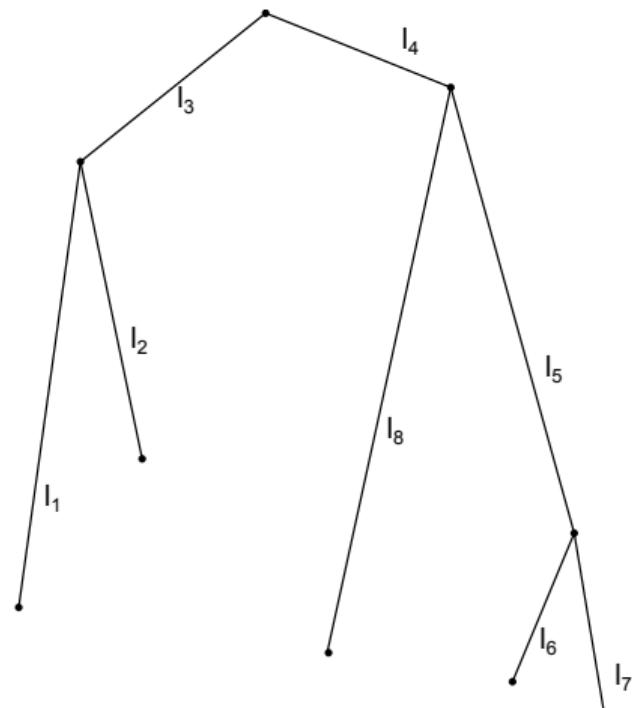
$$\pi = (s, r)$$

The two-state model is always time reversible.

# Likelihood of a tree

background reading: Ewens and Grant (2005), 15.7

- simplifying assumption: evolution at different branches is independent
- suppose we know probability distributions  $v_t$  and  $v_b$  over states at top and bottom of branch  $l_k$
- $\mathcal{L}(l_k) = v_t^T P(l_k) v_b$



# Likelihood of a tree

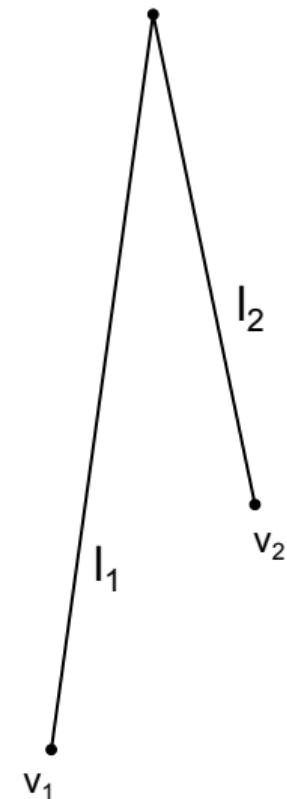
- likelihoods of states (0, 1) at root are

$$v_1^T P(l_1) v_2^T P(l_2)$$

- log-likelihoods

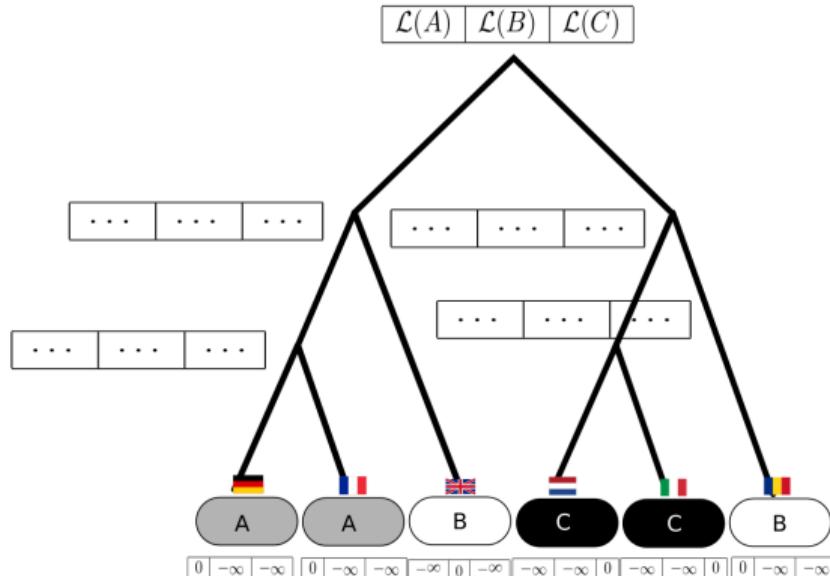
$$\log(v_1^T P(l_1)) + \log(v_2^T P(l_2))$$

- log-likelihood of larger tree: recursively apply this method from tips to root



# Likelihood of a tree

$$\mathcal{L}(\text{mother})_i = \prod_{d \in \text{daughters}} \sum_{1 \leq j \leq n} (P(t)_{i,j} \mathcal{L}(d)_j),$$



# (Log-)Likelihood of a tree

- overall likelihood for entire tree depends on probability distribution on root
- if we assume that root node is in equilibrium:

$$\mathcal{L}(\text{tree}) = (s, r)^T \mathcal{L}(\text{root})$$

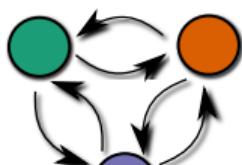
- does not depend on location of the root ( $\rightarrow$  time reversibility)
- this is for one character — likelihood for all data is product of likelihoods for each character

# (Log-)Likelihood of a tree

- likelihood of tree depends on
  - branch lengths
  - rates for each character
- likelihood for tree *topology*:

$$\mathcal{L}(\text{topology}) = \max_{l_k: k \text{ is a branch}} \mathcal{L}(\text{tree} | \vec{l}_k)$$

## Markov process



## Phylogeny

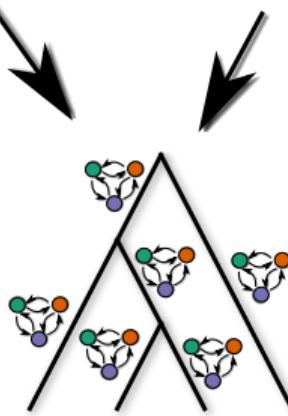
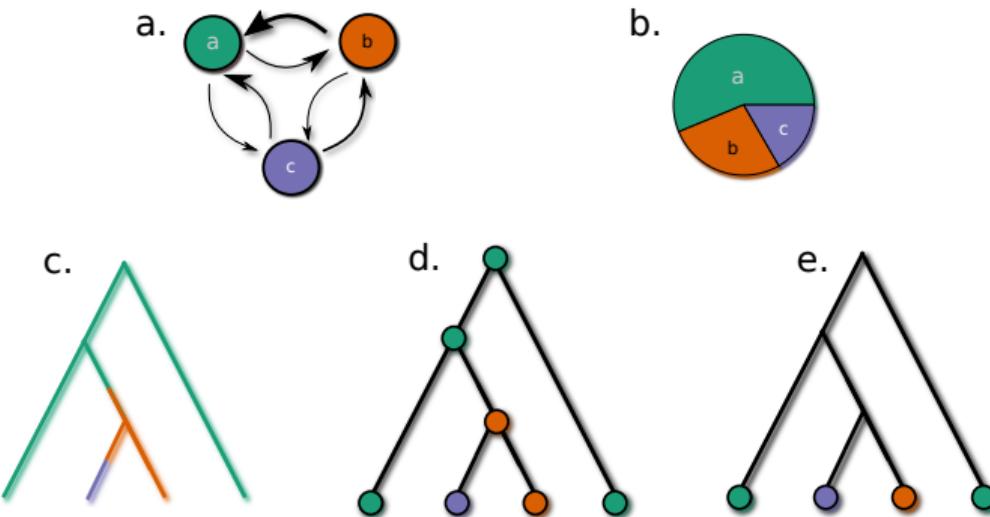
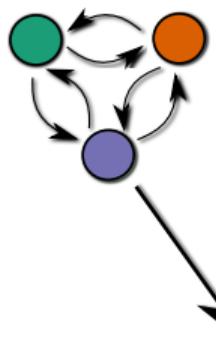


Figure: Schematic structure of the phylogenetic CTMC model. Independent but identical instances of



**Figure:** a. CTMC b. Equilibrium distribution c. Fully specified history of a phylogenetic Markov chain  
d. Marginalizing over events at branches e. Marginalizing over states at internal nodes

## Markov process



## Phylogenies

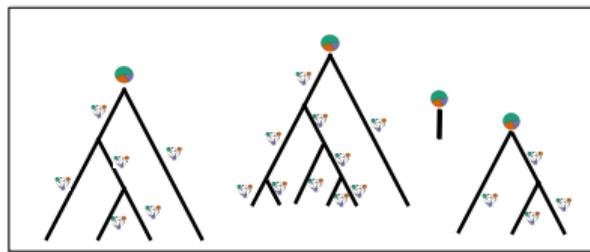
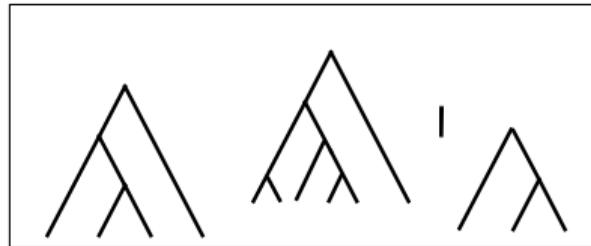
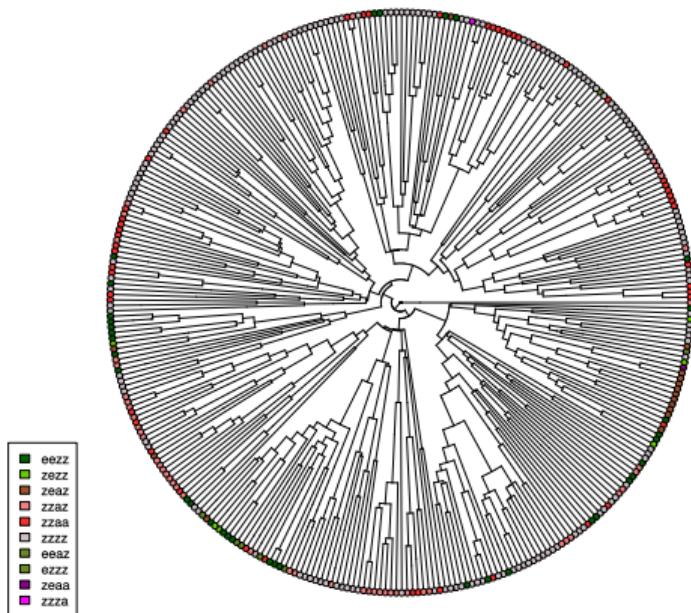


Figure: Phylogenetic Markov CTMC with a collection of phylogenies

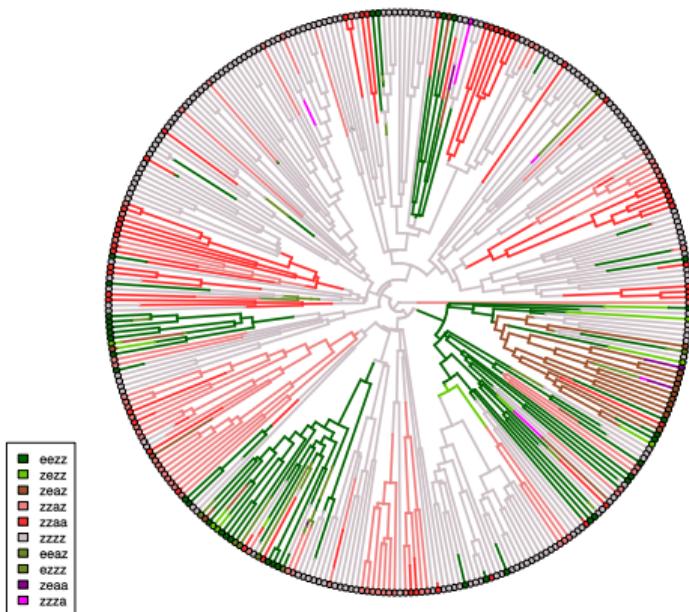
# Estimating rates of change

- if phylogeny and states of extant languages are known...



# Estimating rates of change

- if phylogeny and states of extant languages are known...
- ... transition rates and ancestral states can be estimated based on Markov model

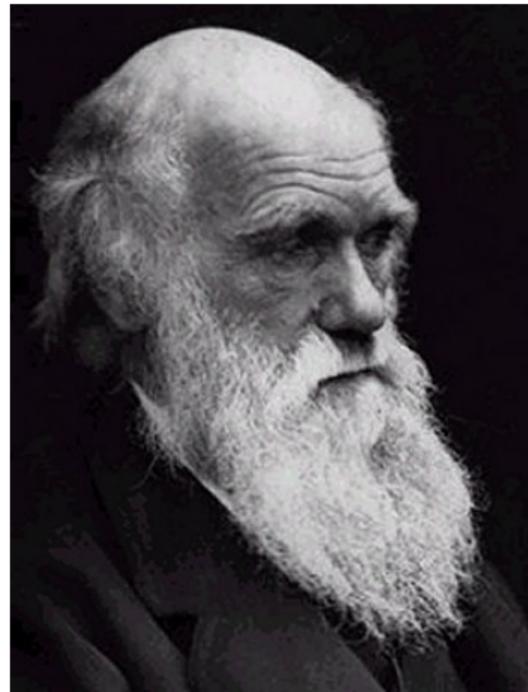


# Language change and evolution

*"The formation of different languages and of distinct species, and the proofs that both have been developed through a gradual process, are curiously parallel. [...] We find in distinct languages striking homologies due to community of descent, and analogies due to a similar process of formation. The manner in which certain letters or sounds change when others change is very like correlated growth. [...] The frequent presence of rudiments, both in languages and in species, is still more remarkable. [...]*

*Languages, like organic beings, can be classed in groups under groups; and they can be classed either naturally according to descent, or artificially by other characters. Dominant languages and dialects spread widely, and lead to the gradual extinction of other tongues."*

(Darwin, The Descent of Man)



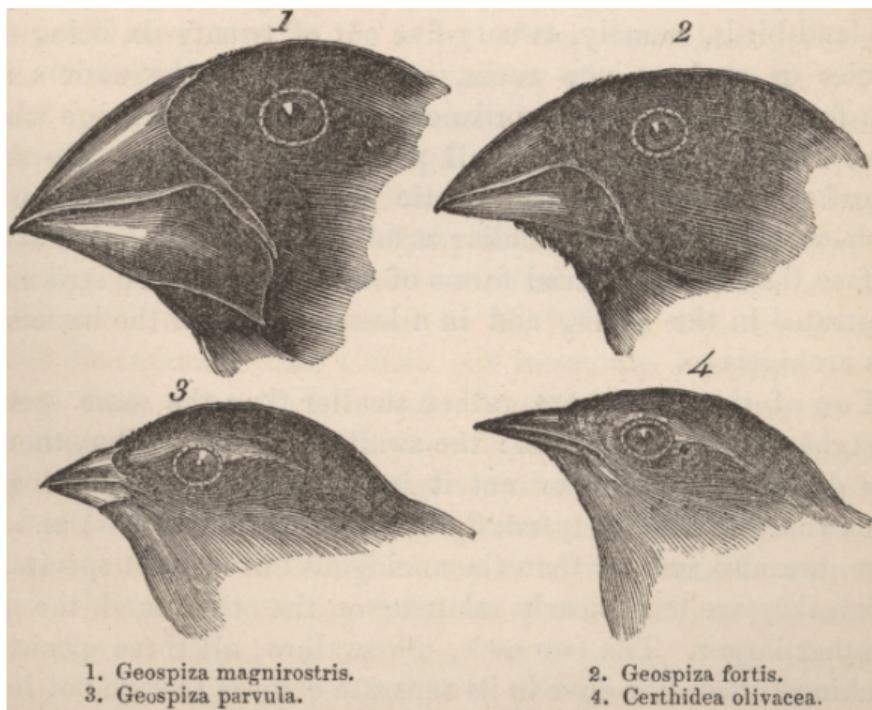
# Language change and evolution

Vater Unser im Himmel, geheiligt werde Dein Name

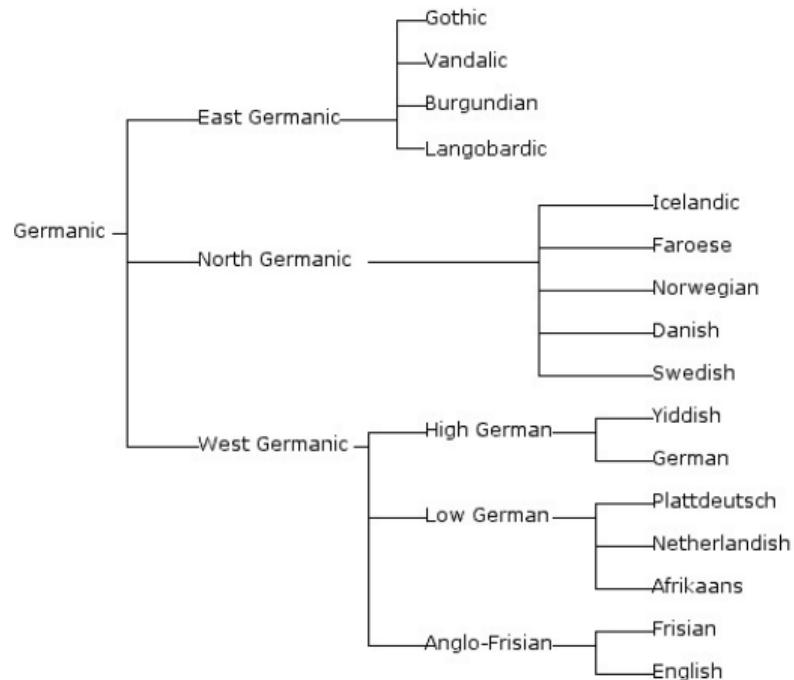
Onze Vader in de Hemel, laat Uw Naam  
geheiligt worden

Our Father in heaven, hallowed be your name

Fader Vor, du som er i himlene! Helliget vorde  
dit navn



# Language change and evolution



# Language change and evolution

*Mittelhochdeutsch:*

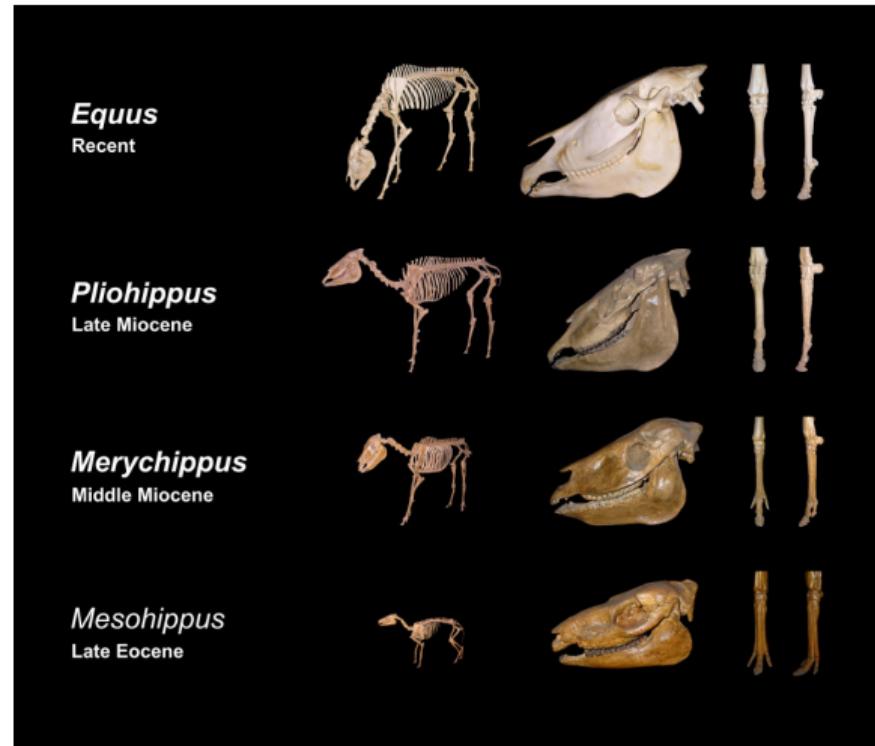
Got vater unser, dâ du bist in dem himelrîche  
gewaltic alles des dir ist, geheiligtô werde  
dîn nam

*Althochdeutsch:*

Fater unser thû thâr bist in himile, si giheilagôt  
thîn namo

*Gotisch:*

Atta unsar þu in himinam, weihnai namo þein



# Convergent evolution

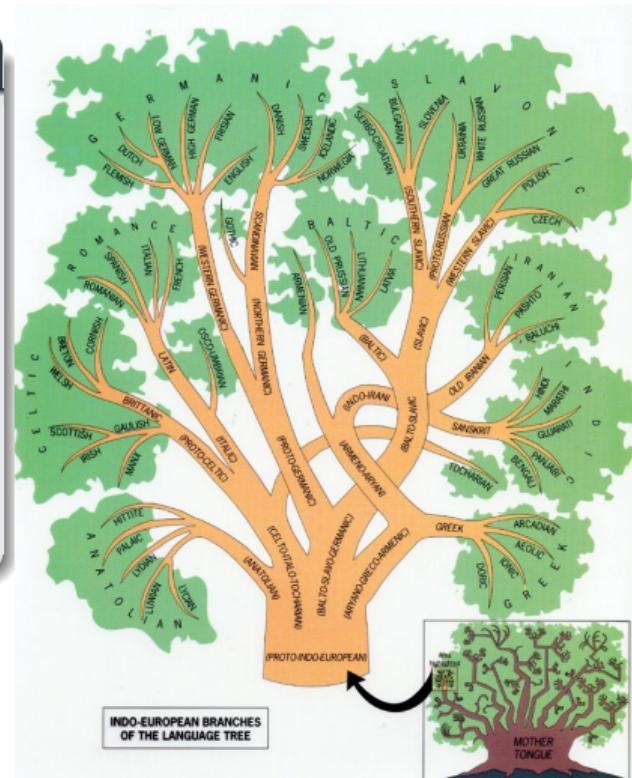


- Old English *docga* > English *dog*
- Proto-Paman \**gudaga* > Mbabaram *dog* ('dog')

# Language phylogeny

## Comparative method

- ① identifying *cognates*, i.e. obviously related morphemes in different languages, such as *new/nowy*, *two/dwa*, or *water/voda*
- ② reconstruction of *common ancestor* and *sound laws* that explain the change from reconstructed to observed forms
- ③ applying this iteratively leads to phylogenetic language trees

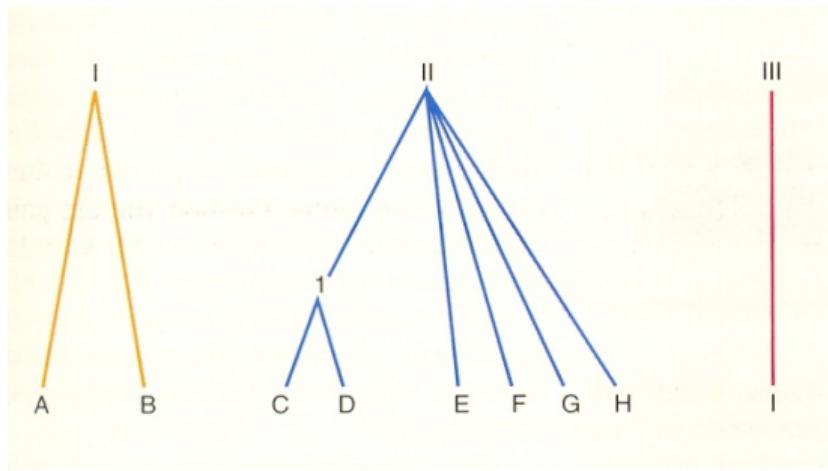


# Similarity between languages

Eine Klassifikationsübung nach der vergleichenden Methode à la Merritt Ruhlen:

Sprache	zwei	drei	ich	du	wer?	nicht	Mutter	Vater	Zahn	Herz	Fuß	Maus	er trägt
A	?iθn-	θalāθ-	-ni	-ka	man	lā	?umm-	abū	sinn	lubb	rijl-	fār	yahmil-
B	jn-	šaloš	-ni	-ka	mi	lo	?em	aβ	šen	leβ	regel	ʃakbɔr	nošeh
C	duvā	tráyas	mām	tuvám	kás	ná	mātár	pitár-	dant-	hṛd-	pád	muš-	bháratí
D	duva	θrāyō	mām	tuvəm	čiš	naē-	mātar-	pitar-	dantan-	zərəd	paiðya		baraiti
E	duo	treis	eme	sú	tís	ou(k)	māter	pater	odōn	kardiā	pod-	mūs	phérei
F	duo	trēs	mē	tū	kwis	ne-	māter	pater	dent-	kord-	ped-	mūs	fert
G	twai	θreis	mik	θu	hwas	ni	aiθei	faðar	tunθus	haírtō	fōt		baíriθ
H	dó	trí	-m	tú	kía	ní-	máθir	aθir	dēt	kride	traig	lux	berid
I	iki	üč	ben-i	sen	kim	deyil	anne	baba	diš	kalp	ayak	sičan	tašiyor

# Similarity between languages



Klassifizieren Sie die angegebenen neun Sprachen (von A bis I) in Familien und Unterfamilien und vergleichen Sie den Wortschatz für die 13 Wörter, die hier in phonetischer Umschrift geboten werden. Lösung: Sprache A und B (Arabisch und Hebräisch) gehören zur Familie der semitischen Sprachen. Die sechs Sprachen C bis H (Sanskrit, Awestisch, Altgrie-

chisch, Latein, Gotisch und Altirisch) sind indogermanische Sprachen. I (Türkisch) läßt sich keiner Familie zuordnen. Mit einer längeren Wortliste kann man nach demselben Verfahren die Familien wieder in Überfamilien einteilen usw. Der Stammbaum, den man so erhält, würde dann beweisen, daß alle Sprachen von einer Muttersprache abstammen.

# Similarity between languages

## Multilateraler Sprachenvergleich

Schlichtes Vergleichen einiger Allerweltswörter erhellt bereits die Verwandtschaftsverhältnisse unter den Sprachfamilien Indoeuropäisch (mit den Zweigen Germanisch, Romanisch und Slawisch) sowie Uralisch-Jukagirisch und Baskisch.

Sprachfamilie	Sprache	eins	zwei	drei	Kopf	Auge	Nase	Mund
<i>Germanisch</i>	Schwedisch	en	tvo	tre	hyvud	øga	næsa	mun
	Niederländisch	ēn	tvē	dri	hōft	ōx	nōs	mont
	Englisch	wən	tū	θri	hed	ai	nouz	mauθ
	Deutsch	ains	tsvai	drai	kopf	augə	nāzə	munt
<i>Romanisch</i>	Französisch	œ/yn	dø	trwa	t̪et	œj	ne	buš
	Italienisch	uno	due	tre	testa	ok̪jo	nasō	bōka
	Spanisch	uno	dos	tres	kabesa	oxo	nasō	boka
	Rumänisch	un	doi	trei	kap	oki	nas	gure
<i>Slawisch</i>	Polnisch	jeden	dva	tri	gwova	oko	nos	usta
	Russisch	adin	dva	tri	galava	oko	nos	rot
	Bulgarisch	edin	dva	tri	glava	oko	nos	usta
<i>Uralisch-Jukagirisch</i>	Finnisch	yksi	kaksi	kolme	p̄e	silmæ	nenæ	sū
	Estnisch	yks	kaks	kolm	pea	silm	nina	sū
<i>Baskisch</i>	Baskisch	bat	bi	hiryr	byry	begi	sydyr	aho

# Language phylogeny

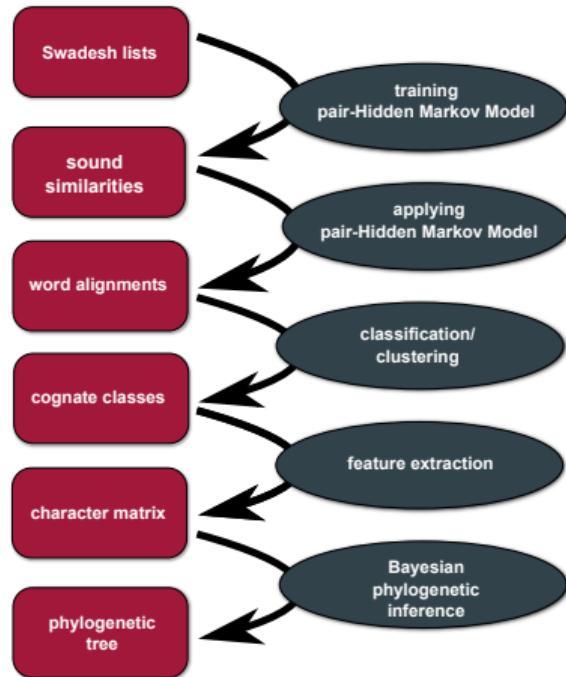
## Scope of the method

- reconstructed vocabulary shrinks with growing time depth
- maximal time horizon seems to be about 8,000 years
- grammatical morphemes and categories arguably more stable and less apt to borrowing
- problem here: limited number of features, cross-linguistic variation constrained by language universals, frequently convergent evolution
- comparative method is hard to apply in regions with high linguistic diversity and without written documents (Paleo-America, Papua)
- tree structure might be inappropriate if there is a significant effect of language contact (cf. Australia)

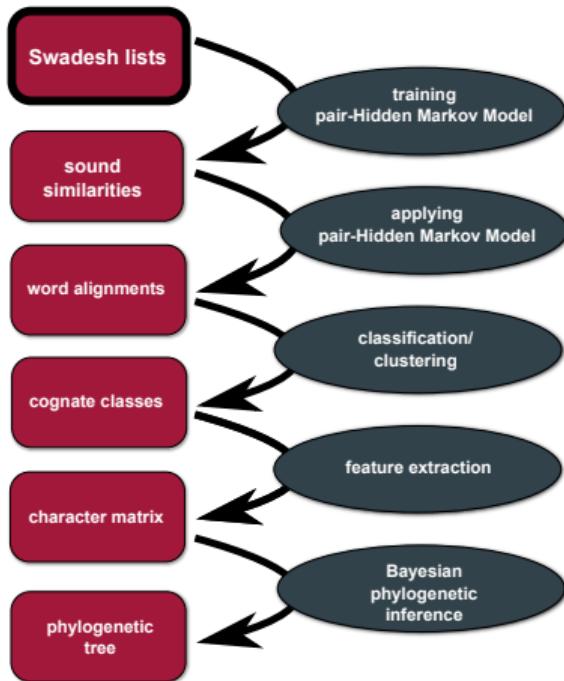
# Computational Methods

- both cognate detection and tree construction lend themselves to algorithmic implementation
- Advantages:
  - easy to scale up
  - comparability of results
  - affords statistical evaluation
- Disadvantages:
  - cognacy judgments require lots of linguistic insight and experience
  - tree construction should be subject to historical (including archeological) and geographical plausibility

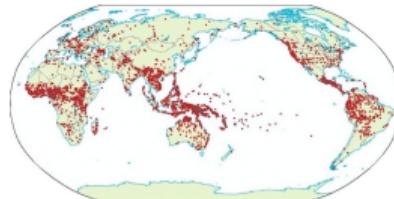
# From words to trees



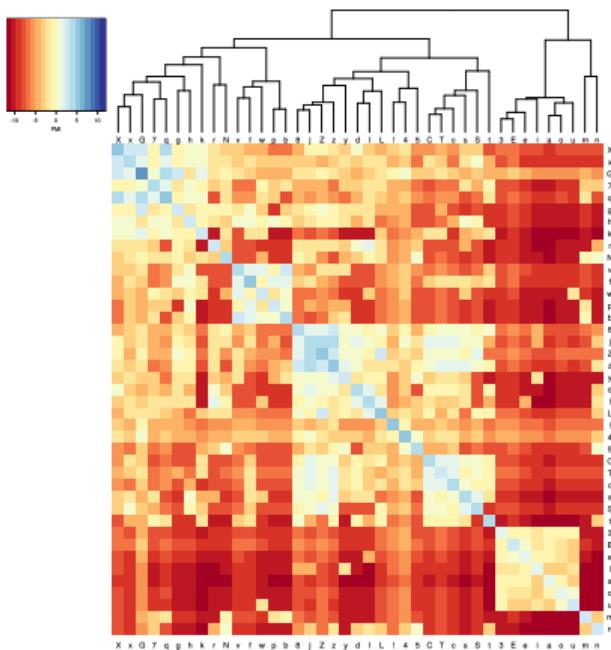
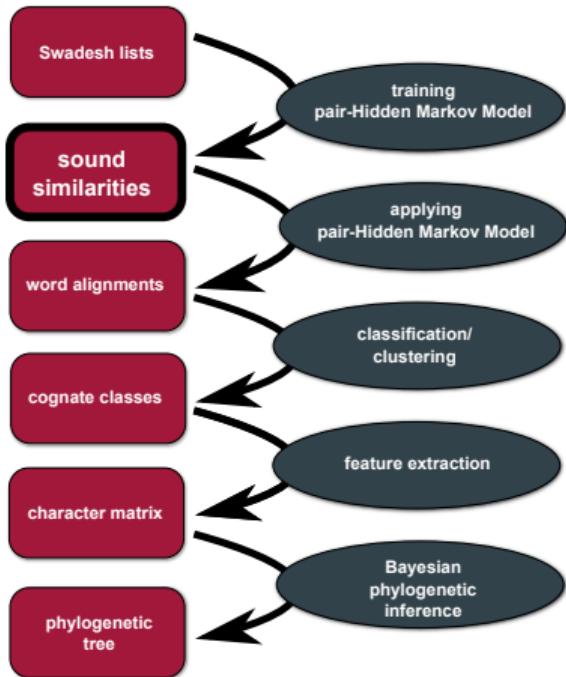
# From words to trees



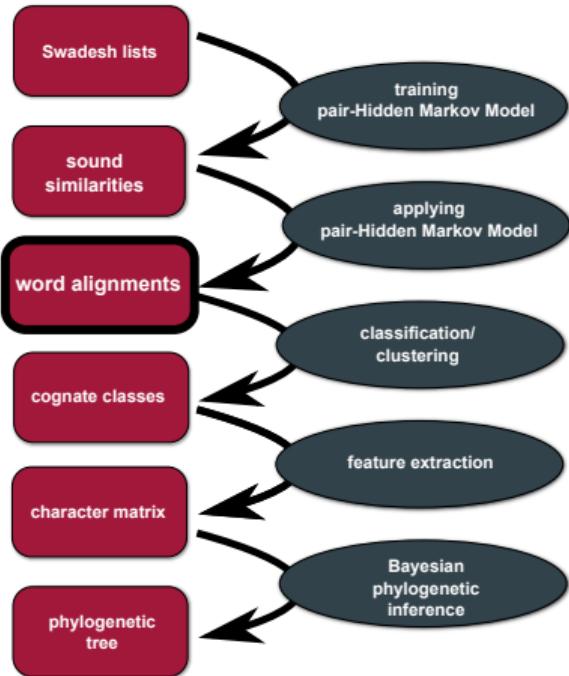
concept	Latin	English
I	ego	Ei
you	tu	yu
we	nos	wi
one	unus	w3n
two	duo	tu
person	persona, homo	pers3n
fish	piskis	fiS
dog	kanis	dag
louse	pedikulus	laus
tree	arbor	tri
leaf	foly~u*	lif
skin	kutis	skin
blood	saNgw~is	bl3d
bone	os	bon
horn	kornu	horn
ear	auris	ir
eye	okulus	Ei



# From words to trees

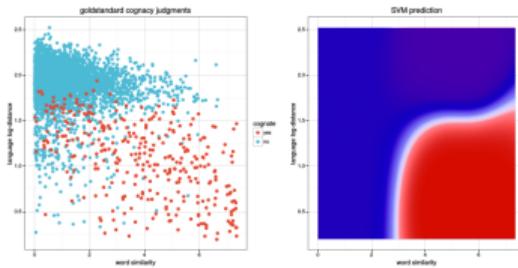
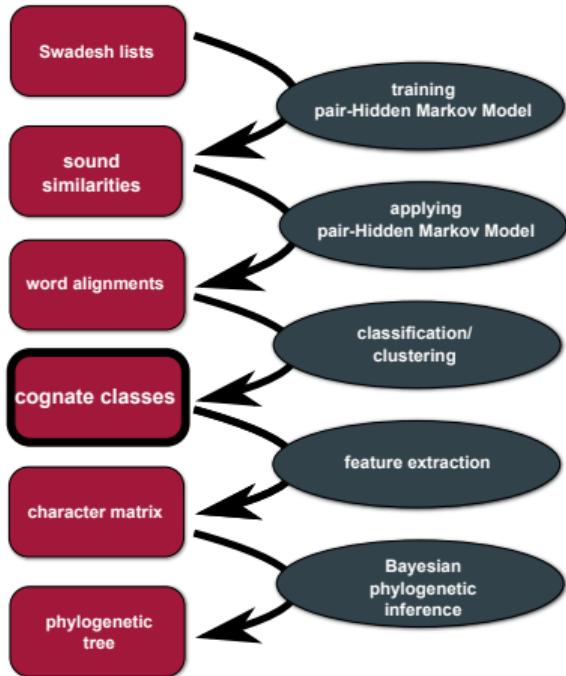


# From words to trees



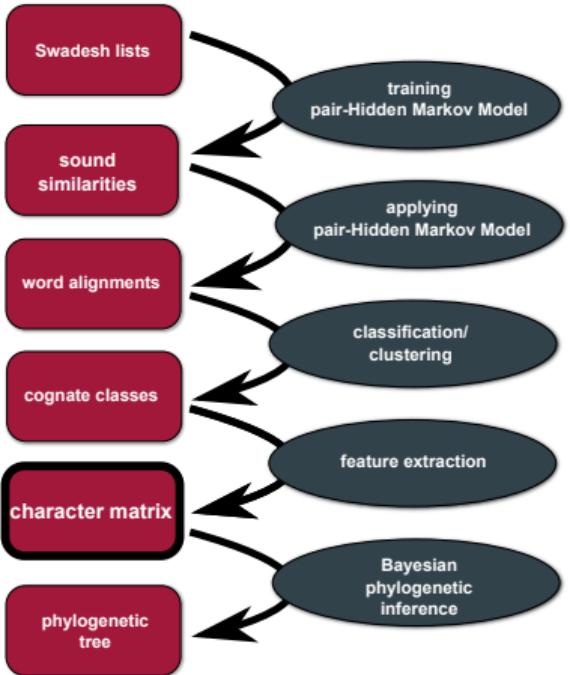
Language	<i>fish:z</i>	<i>tongue:1</i>	<i>smoke:1</i>
Abui-Atangmelang	-af-u	tal-i-fi--	
Abui-Fuimelang	-af-u	awai--b-a-n-o-7o-	
Adang	aab--	tal-E-b---	--ad--b-a-n-a-nka-
Blagar-Bakalang	-ab--	--j-e-bur-	-----b-e-n-a-xa-
Blagar-Bama	aab--	teg-e-bur-	-----b-e-n-a-nka-
Blagar-Kulijahi	-ab--	tej-e-bur-	-----b-e-n-a-q--
Blagar-Nule	aab--	tej-e-bur-	--ad--b-e-n-a-nka-
Blagar-Tuntuli	aab--	tej-e-bur-	a-adgeb-a-n-a-x--
Blagar-Warsalelang	-ab--	tel-e-bur-	a-ad--b-a-n-a-x--
Bunaq			-----b-o-t-o-h--
Deing	haf--		-----buu-n----
Hamap	7ab--	nar-ø-buN-	-----b-a-n-o-7--
Kabola	hab--	tal-e-b---	aval--b-e-n-e-7o-
Kaera-Padangsul	-ab--	talee-b---	a-ad--b-e-naa-x--
Kafoa	-afUi	tal-i-p---	-----f-o-n-a----
Kamang	-ap-i	nal---pu--	-----p-u-n----a
Kiraman	-Eb--	nal-i-bar-	--ar--b-a-n-o-kan
Klon	-eb-i	gel-E-b---	--ed-ab-o-n-----
Kui	-eb--	tal-i-ber-	--ar--b-o-n-o-k--
Kula	-ap-i	-il-I-p---	-----p-n-ekka-
Nedebang	aaf-i	gel-e-fu--	--ar-ab-u-n-----
Reta	aab--	nal-e-bul-	a-ad--b-o-n-a----
Sar-Adiabang	haf--	--p-e-fal-	--ar--buu-n-----
Sar-Nule	haf--	nal-e-faj-	
Sawila	-ap-i	gal-impruru	-----p-u-n-a-ka-
Teiwa-Madar	xaf--	gel-i-vi--	-----buu-n-----
Wersing	-ap-i	nej-e-bur-	--ad-ap-u-n-a-k--
Wpantar	hap--	nal-e-bu--	-----b-unna----

# From words to trees

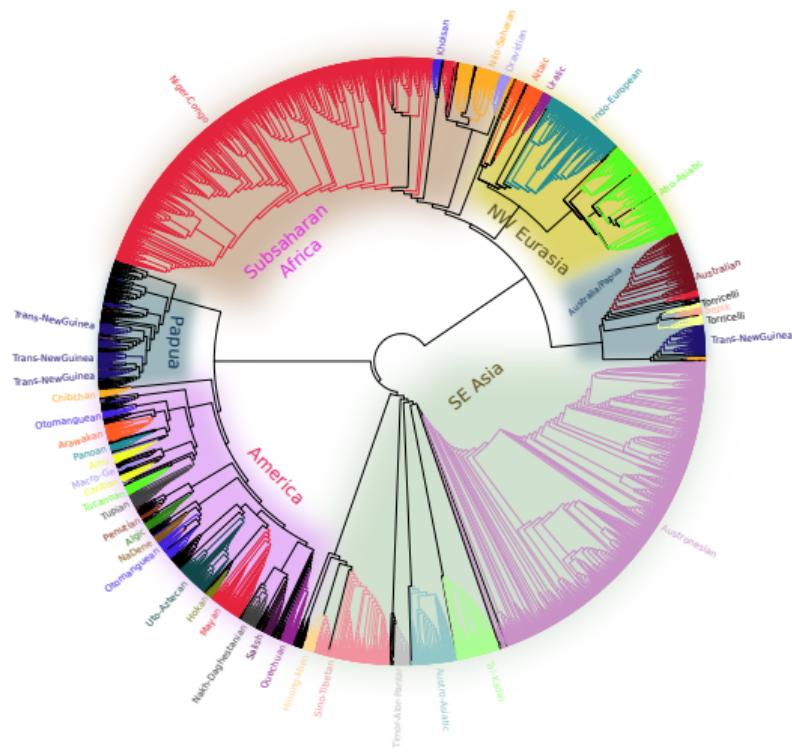
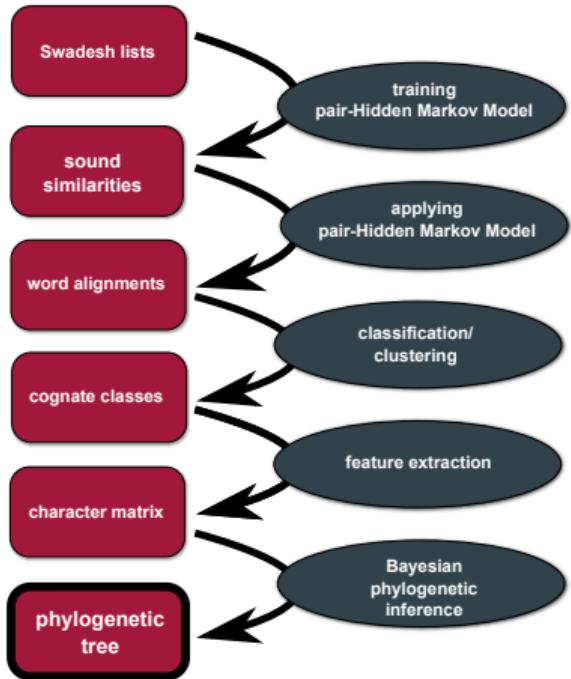


	English	Spanish	Modern Greek	Standard German
I	Ei:A	yo:B	exo:C	iX:D
you	yu:A	ustet:B, tu:C	esi:D	du:E
we	wi:A	nosotros:B	emis:C	vir:A
one	w3n:A	uno:B	enas:C, ena:C	ains:D
two	tu:A	dos:B	8y~o:C, 8io:D	cva:i:B
person	pers3n:A	persona:A	an8~ropos:B	mEnS:C
fish	fis:A	peskado:A, pes:A	psari:B	fi:S:A
dog	dag:A	pero:B	sTili:C, sTilos:C	hund:D
come	k3m:A	veni:B	erx~o:C	kh~om3n:A
sun	s3n:A	sol:B	ily~os:C, iLos:C	zon3:A
star	star:A	estreya:A	asteri:A, astro:A	StErn:A
water	wat3r:A	agw~a:B	nero:C	vas3r:A
stone	ston:A	piedra:B	petra:B	Stain:A
fire	f8ir:A	fuego:B	foty~a:C	foia:D
path	p88:A	senda:B	8romos:C	pf~at:A, vek:D
mountain	maunt3n	sero:B, monta5a:A	vuno:C, oros:D	bErk:E
full	ful:A	yeno:B	yematos:C, pliriss:D	fol:A
new	nu:A	nuevo:A	neos:A, Tenury~os:B	noi:A
name	nem:A	nombre:A	onoma:A	nam3:A

# From words to trees



# From words to trees



# From word lists to distances

# The Automated Similarity Judgment Program

- Project at MPI EVA in Leipzig around Søren Wichmann
- covers more than 6,000 languages and dialects
- basic vocabulary of 40 words for each language, in uniform phonetic transcription
- freely available

**used concepts:** *I, you, we, one, two, person, fish, dog, louse, tree, leaf, skin, blood, bone, horn, ear, eye, nose, tooth, tongue, knee, hand, breast, liver, drink, see, hear, die, come, sun, star, water, stone, fire, path, mountain, night, full, new, name*

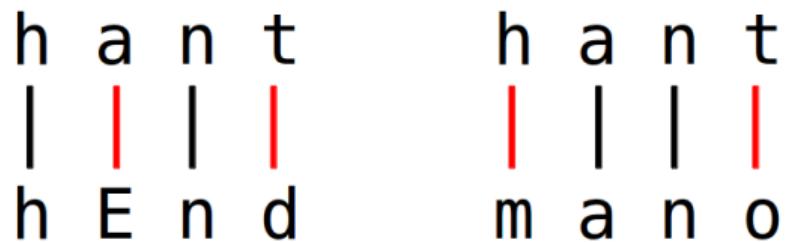
# Automated Similarity Judgment Project

<i>concept</i>	Latin	English
<i>I</i>	ego	Ei
<i>you</i>	tu	yu
<i>we</i>	nos	wi
<i>one</i>	unus	w3n
<i>two</i>	duo	tu
<i>person</i>	persona, homo	pers3n
<i>fish</i>	piskis	fiS
<i>dog</i>	kanis	dag
<i>louse</i>	pedikulus	laus
<i>tree</i>	arbor	tri
<i>leaf</i>	foly~u*	lif
<i>skin</i>	kutis	skin
<i>blood</i>	saNgw~is	bl3d
<i>bone</i>	os	bon
<i>horn</i>	kornu	horn
<i>ear</i>	auris	ir
<i>eye</i>	okulus	Ei

<i>concept</i>	Latin	English
<i>nose</i>	nasus	nos
<i>tooth</i>	dens	tu8
<i>tongue</i>	liNgw~E	t3N
<i>knee</i>	genu	ni
<i>hand</i>	manus	hEnd
<i>breast</i>	pektus, mama	brest
<i>liver</i>	yekur	liv3r
<i>drink</i>	bibere	drink
<i>see</i>	widere	si
<i>hear</i>	audire	hir
<i>die</i>	mori	dEi
<i>come</i>	wenire	k3m
<i>sun</i>	sol	s3n
<i>star</i>	stela	star
<i>water</i>	akw~a	wat3r
<i>stone</i>	lapis	ston
<i>fire</i>	iNnis	fEir

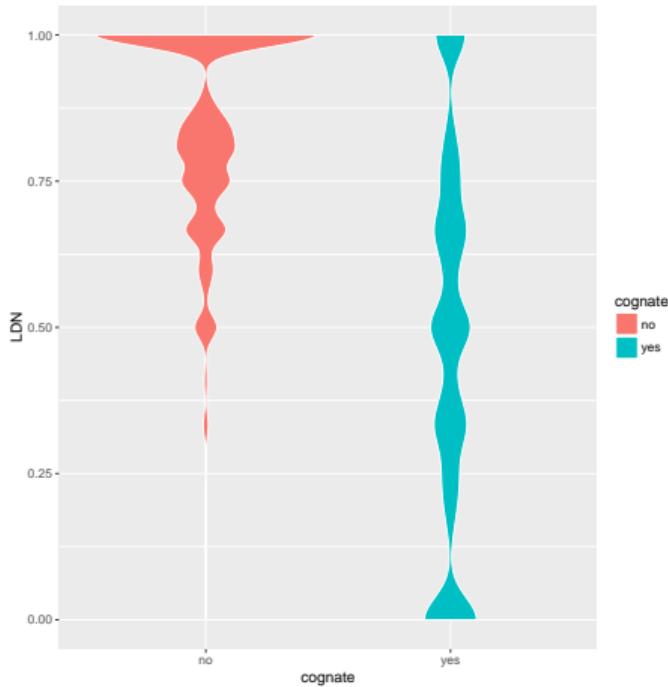
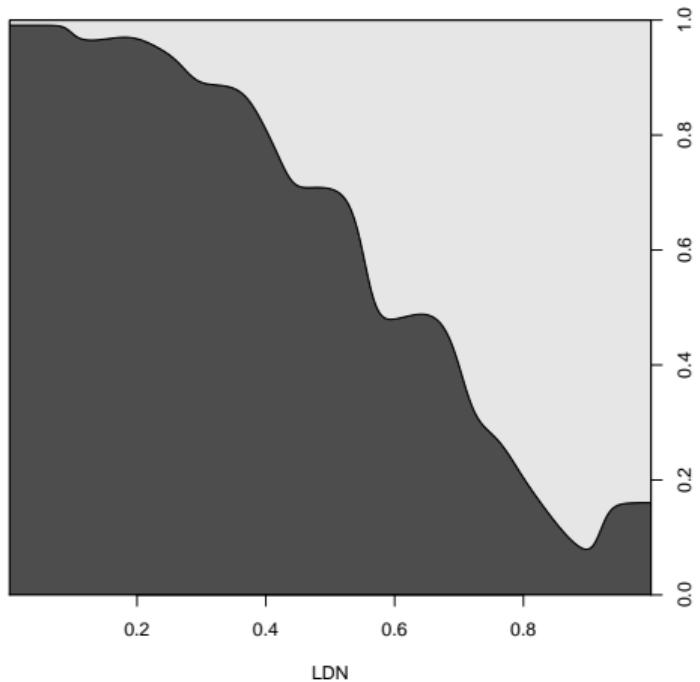
# Word distances

- based on string *alignment*
- baseline: Levenshtein alignment ⇒ count matches and mis-matches



- too crude as it totally ignores sound correspondences

# How well does normalized Levenshtein distance predict cognacy?



# Problems

- binary distinction: match vs. non-match
- frequently genuine sound correspondences in cognates are missed:

c	v	a	i	n	a	z	3	-	-	-	f	i	S
-	-	t	u	n	-	o	s	p	i	s	k	i	s

- corresponding sounds count as mismatches even if they are aligned correctly

h	a	n	t	h	a	n	t
h	E	n	d	m	a	n	o

- substantial amount of chance similarities

# Capturing sound correspondences

- weighted alignment using **Pointwise Mutual Information** (PMI, a.k.a. *log-odds*):

$$s(a, b) = \log \frac{p(a, b)}{q(a)q(b)}$$

- $p(a, b)$ : probability of sound  $a$  being etymologically related to sound  $b$  in a pair of cognates
- $q(a)$ : relative frequency of sound  $a$
- **Needleman-Wunsch algorithm**: given a matrix of pairwise PMI scores between individual symbols and two strings, it returns the alignment that maximizes the aggregate PMI score
- but first we need to estimate  $p(a, b)$  and  $q(a), q(b)$  for all soundclasses  $a$  and  $b$
- $q(a)$ : relative frequency of occurrence of segment  $a$  in all words in ASJP
- $p(a, b)$ : that's a bit more complicated...

# Substitution matrix for the ASJP data

1. identify large sample of pairs of closely related languages (using expert information or heuristics based on aggregated Levenshtein distance)

An.NORTHERN\_PHILIPPINES.CENTRAL\_BONTOC  
 An.MESO-PHILIPPINE.NORTHERN\_SORSOGON

WF.WESTERN\_FLY.IAMEGA  
 WF.WESTERN\_FLY.GAMAEWE

Pan.PANOAN.KASHIBO\_BAJO\_AGUAYTIA  
 Pan.PANOAN.KASHIBO\_SAN\_ALEJANDRO

AA.EASTERN\_CUSHITIC.KAMBAATA\_2  
 AA.EASTERN\_CUSHITIC.HADIYYA\_2

ST.BAI.QILIQIAO\_BAI\_2  
 ST.BAI.YUNLONG\_BAI

An.SULAWESI.MANDAR  
 An.OCEANIC.RAGA

An.SULAWESI.TANETE  
 An.SAMA-BAJAW.BOEPINANG\_BAJAU

An.SOUTHERN\_PHILIPPINES.KAGAYANEN  
 An.NORTHERN\_PHILIPPINES.LIMOS\_KALINGA

An.MESO-PHILIPPINE.CANIPAAN\_PALAWAN  
 An.NORTHWEST\_MALAYO-POLYNESIAN.LAHANAN

NC.BANTOID.LIFONGA  
 NC.BANTOID.BOMBOMA\_2

IE.INDIC.WAD\_PAGGA  
 IE.INDIC.TALAGANG\_HINDKO

NC.BANTOID.LINGALA  
 NC.BANTOID.LIFONGA

An.CENTRAL\_MALAYO-POLYNESIAN.BALILEDO  
 An.CENTRAL\_MALAYO-POLYNESIAN.PALUE

AuA.MUNDA.HO  
 AuA.MUNDA.KORKU

# Substitution matrix for the ASJP data

2. pick a concept and a pair of related languages at random
  - languages: Pen.MAIDUAN.MAIDU\_KONKAU, Pen.MAIDUAN.NE\_Maidu
  - concept: *one*
3. find corresponding words from the two languages:
  - nisam, niSem
4. do Levenshtein alignment

n	i	s	a	m
n	i	S	e	m

5. for each sound pair, count number of correspondences
  - nn: 1; ii: 1; sS: 1; ae: 1; mm: 1

# Finding the best alignment

- Dynamic Programming

	—	m	E	n	S
—	0	-2.5	-4.1	-5.7	-7.3
m	-2.5				
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	—	m	E	n	S
—	0	-2.5	-4.1	-5.7	-7.3
m	-2.5				
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	—	m	E	n	S
—	0	-2.5	-4.1	-5.7	-7.3
m	-2.5				
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	—	m	E	n	S
—	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13			
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13			
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13			
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	—	m	E	n	S
—	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53		
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	—	m	E	n	S
—	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1				
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53			
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65		
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7				
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03			
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05		
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3				
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47			
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75		
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9				

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97			

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15		

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15	5.1	

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15	5.1	8.84

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15	5.1	8.84

- memorizing in each step which of the three cells to the left and above gave rise to the current entry lets us recover the corresponding optimal alignment

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15	5.1	8.84

- memorizing in each step which of the three cells to the left and above gave rise to the current entry lets us recover the corresponding optimal alignment

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15	5.1	8.84

- memorizing in each step which of the three cells to the left and above gave rise to the current entry lets us recover the corresponding optimal alignment

# Finding the best alignment

- Dynamic Programming

	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15	5.1	8.84

- memorizing in each step which of the three cells to the left and above gave rise to the current entry lets us recover the corresponding optimal alignment

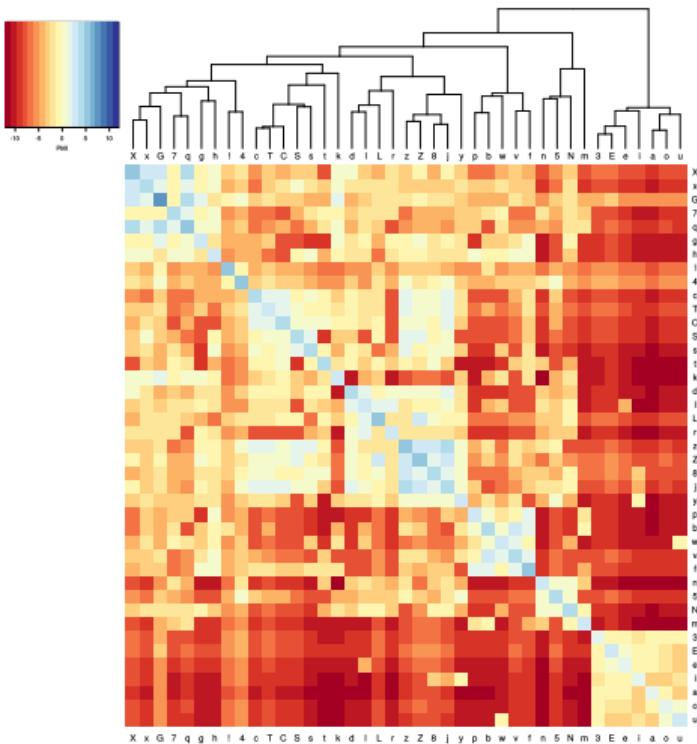
# Finding the best alignment

- Dynamic Programming

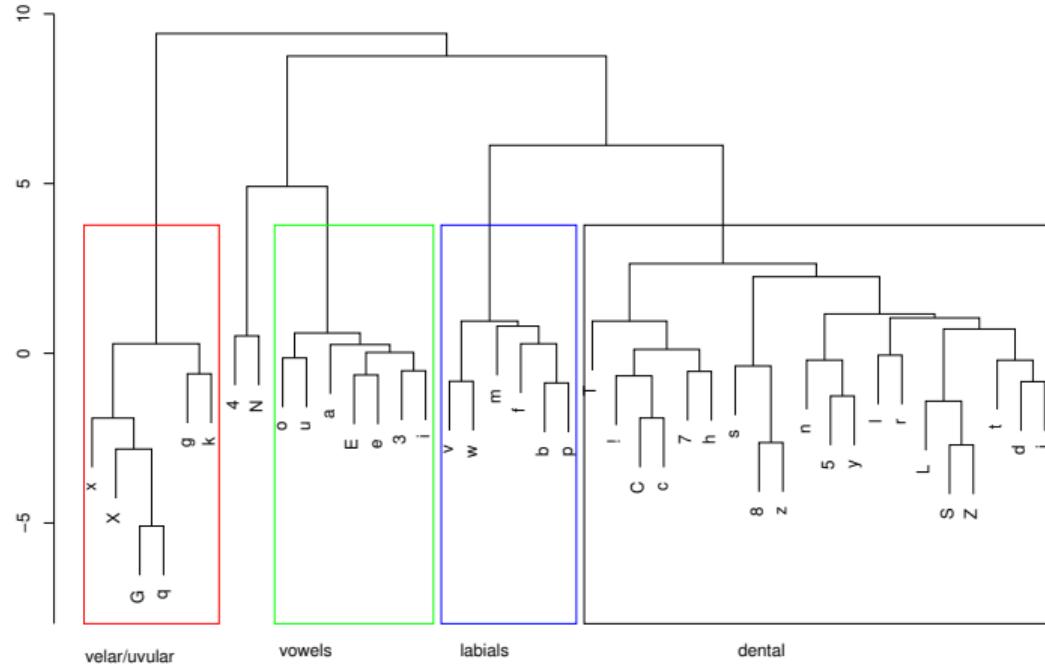
	–	m	E	n	S
–	0	-2.5	-4.1	-5.7	-7.3
m	-2.5	4.13	1.53	0.03	-1.47
e	-4.1	1.53	5.65	3.05	1.55
n	-5.7	0.03	3.05	9.2	6.6
E	-7.3	-1.47	4.75	6.6	7.62
s	-8.9	-2.97	2.15	5.1	8.84

- memorizing in each step which of the three cells to the left and above gave rise to the current entry lets us recover the corresponding optimal alignment

# Evaluation

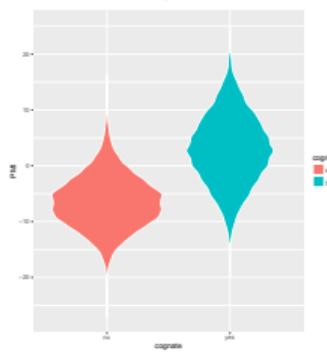
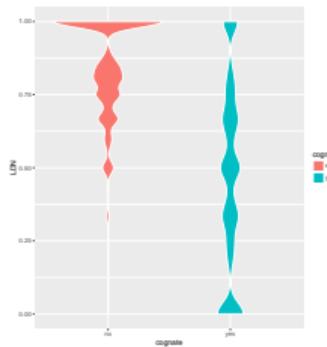
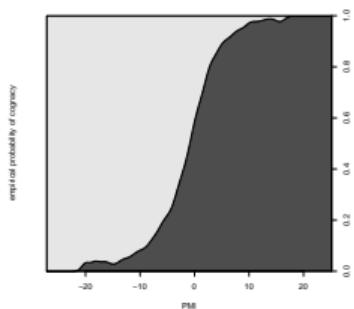
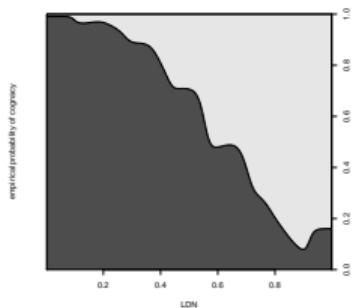


# Evaluation



# How well does PMI similarity predict cognacy?

expert cognacy judgments used as gold standard



# Calibrated PMI similarity

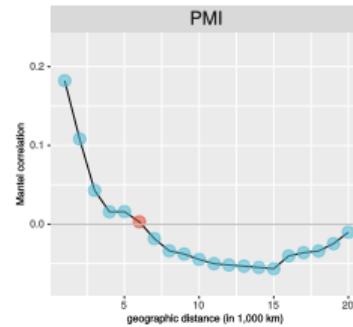
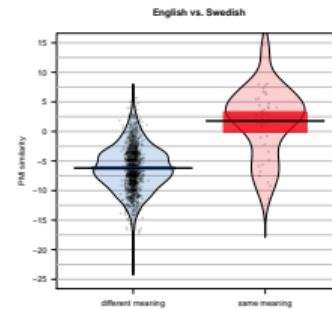
English / Swedish

	Ei	yu	wi	w3n	tu	fiS	...
yog	<b>-7.77</b>	0.75	-7.68	-7.90	-8.57	-10.50	
du	-7.62	<b>0.33</b>	-5.71	-7.41	2.66	-8.57	
vi	-2.72	-2.83	<b>4.04</b>	-1.34	-6.45	0.70	
et	-5.47	-7.87	-5.47	<b>-6.43</b>	-1.83	-4.70	
tvo	-7.91	-4.27	-3.64	-4.57	<b>0.39</b>	-6.98	
fisk	-7.45	-11.2	-3.07	-9.97	-8.66	<b>7.58</b>	
:							

- values along diagonal give similarity between candidates for cognacy (possibility of meaning change is disregarded)
- values off diagonal provide sample of similarity distribution between non-cognates

# Calibrated PMI similarity

- let  $s$  be the PMI-similarity between the English and Swedish word for concept  $c$
- calibrated string similarity:**  $-\log(\text{probability that random word pairs are more similar than } s)$
- language similarity:** average word similarity for all concepts



# Cognate clustering

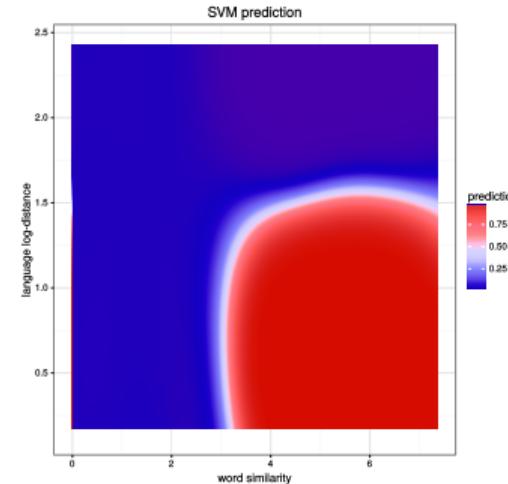
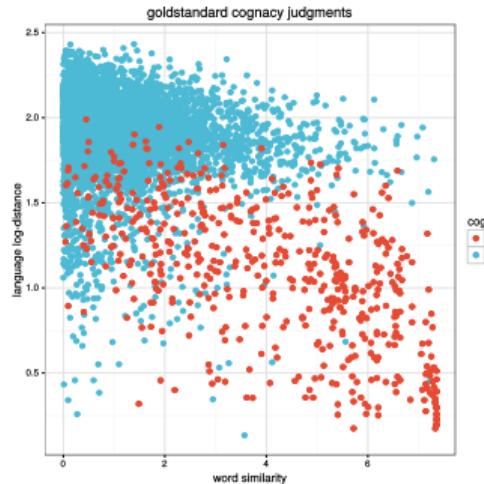
# Cognate clustering

- clustering of ASJP strings into *automatically inferred cognate classes* (Jäger and Sofroniev, 2016; Jäger et al., 2017) (take “cognate” with a grain of salt)
- supervised learning, based on expert cognacy judgments as goldstandard
- sources (only the 40 ASJP concepts were used)

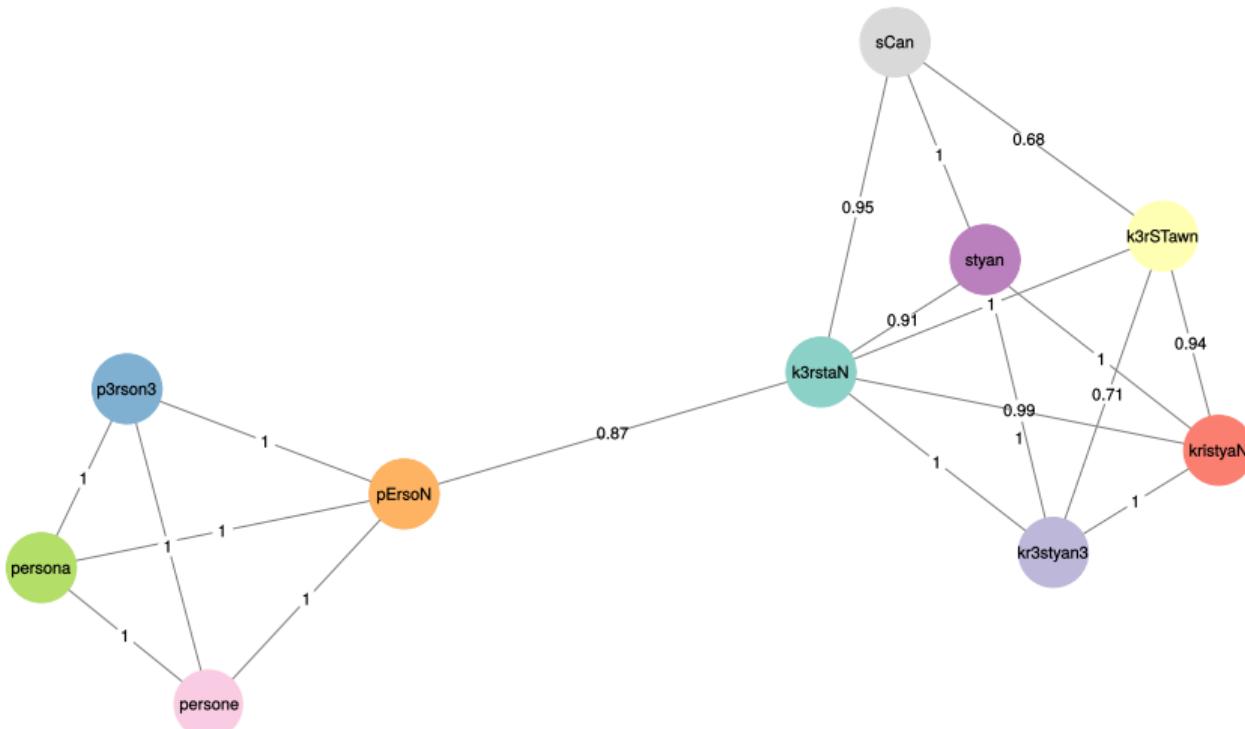
Dataset	Source	Words	Concepts	Languages	Families	Cognate classes
ABVD	Greenhill et al. (2008)	2,306	34	100	Austronesian	409
Afrasian	Militarev (2000)	770	39	21	Afro-Asiatic	351
Chinese	Běijing Dàxué (1964)	422	20	18	Sino-Tibetan	126
Huon	McElhanon (1967)	441	32	14	Trans-New Guinea	183
IELex	Dunn (2012)	2,089	40	52	Indo-European	318
Japanese	Hattori (1973)	387	39	10	Japonic	74
Kadai	Peiros (1998)	399	40	12	Tai-Kadai	102
Kamasau	Sanders and Sanders (1980)	270	36	8	Torricelli	59
Mayan	Brown et al. (2008)	1,113	40	30	Mayan	241
Miao-Yao	Peiros (1998)	206	36	6	Hmong-Mien	69
Mixe-Zoque	Cysouw et al. (2006)	355	39	10	Mixe-Zoque	79
Mon-Khmer	Peiros (1998)	579	40	16	Austroasiatic	232
ObUgrian	Zhivlov (2011)	769	39	21	Uralic	68
total		10,106	40	318	13	2,311

# Cognate clustering

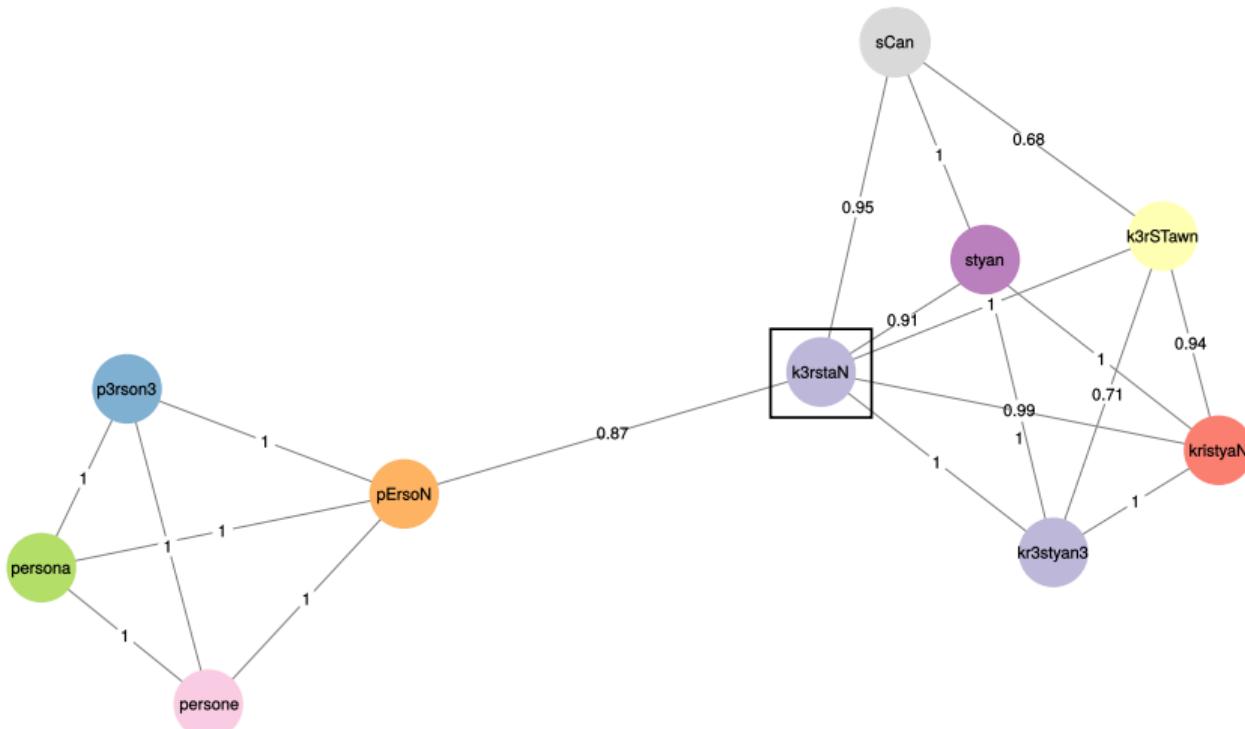
- calibrated word similarity and language similarity were used as predictors to train a *Support Vector Machine* → probability of being cognate for each pair of synonymous ASJP entries
- *Label Propagation* (Raghavan et al., 2007) for clustering
- 0.84 B-cubed F-score with cross-validation on goldstandard data



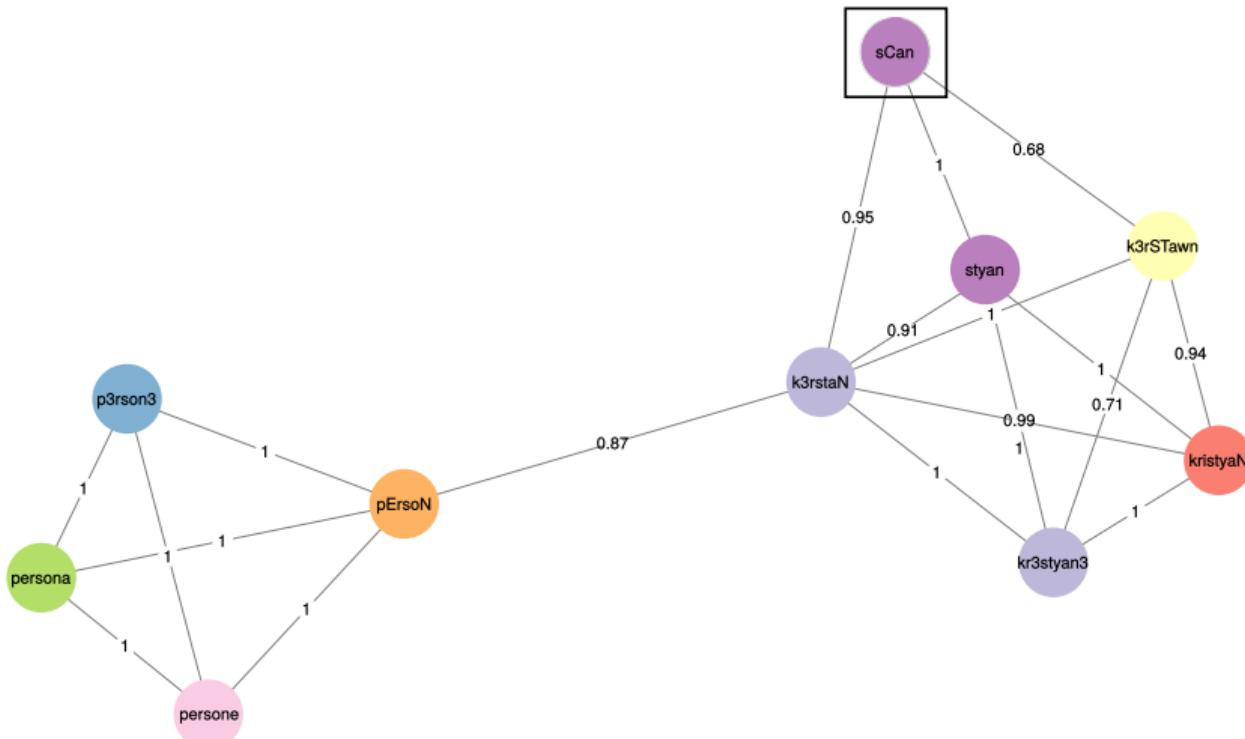
# Clustering via Label Propagation



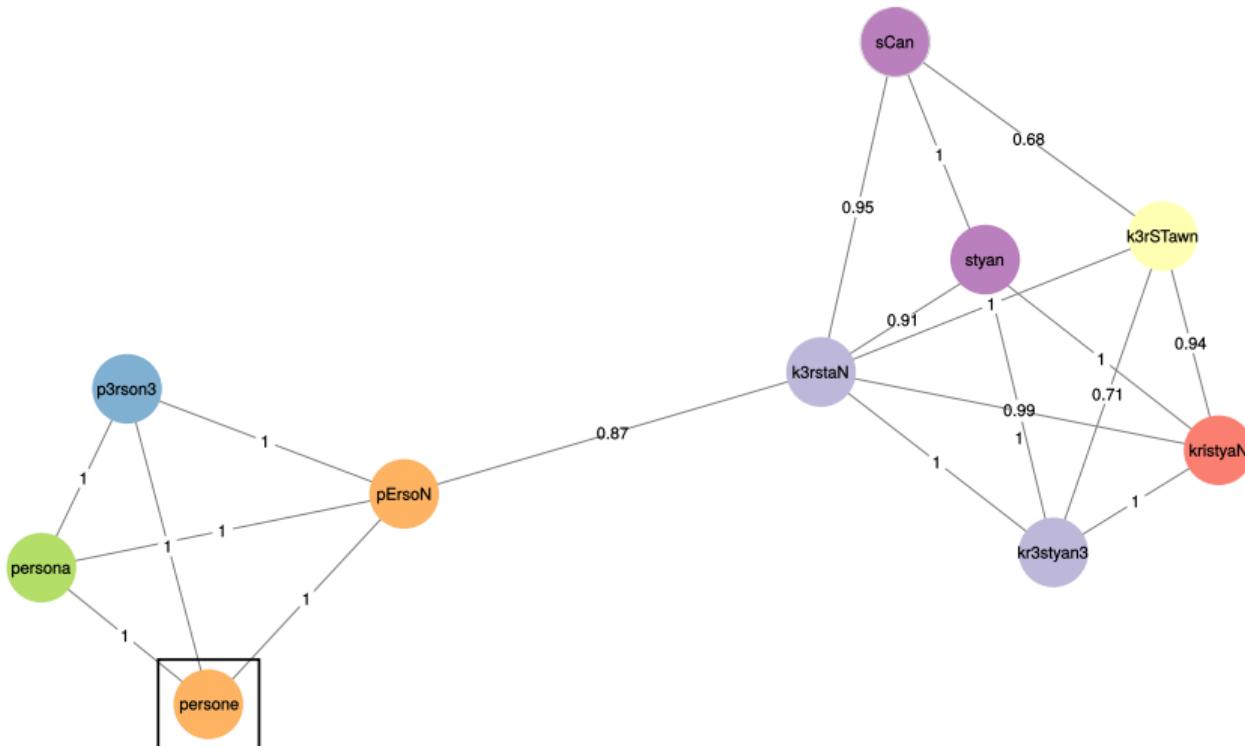
# Clustering via Label Propagation



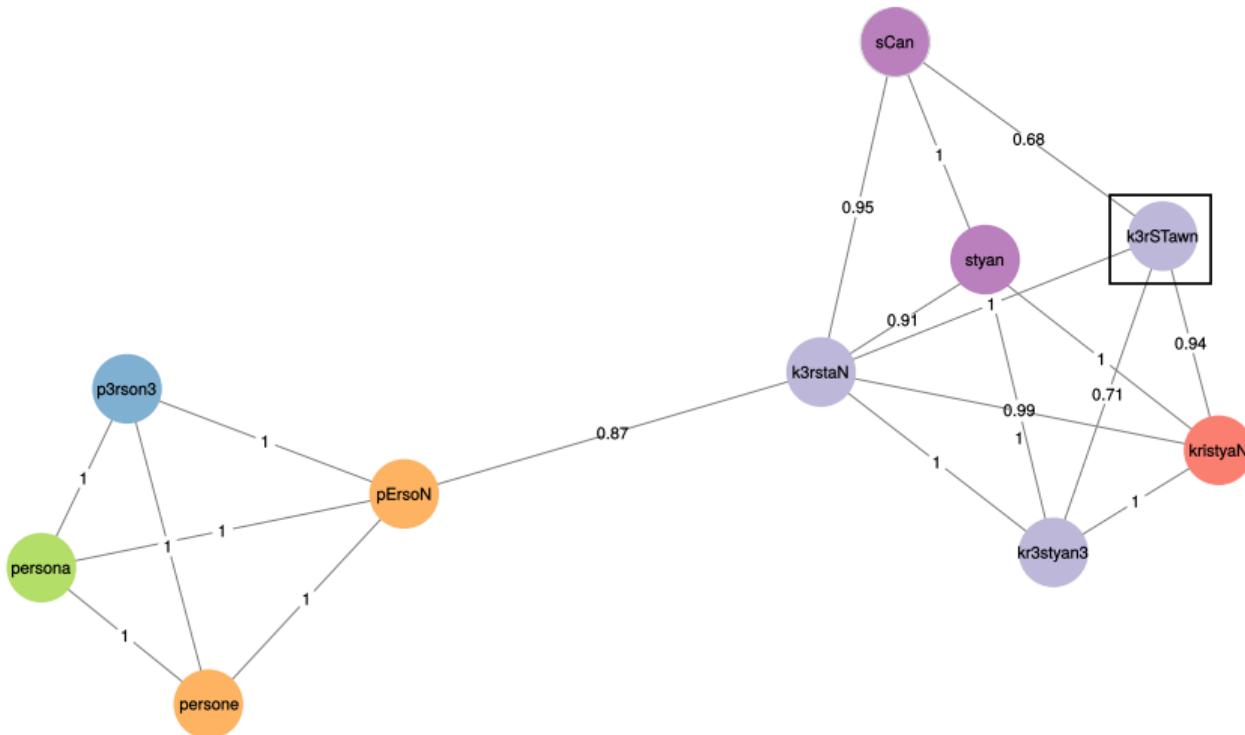
# Clustering via Label Propagation



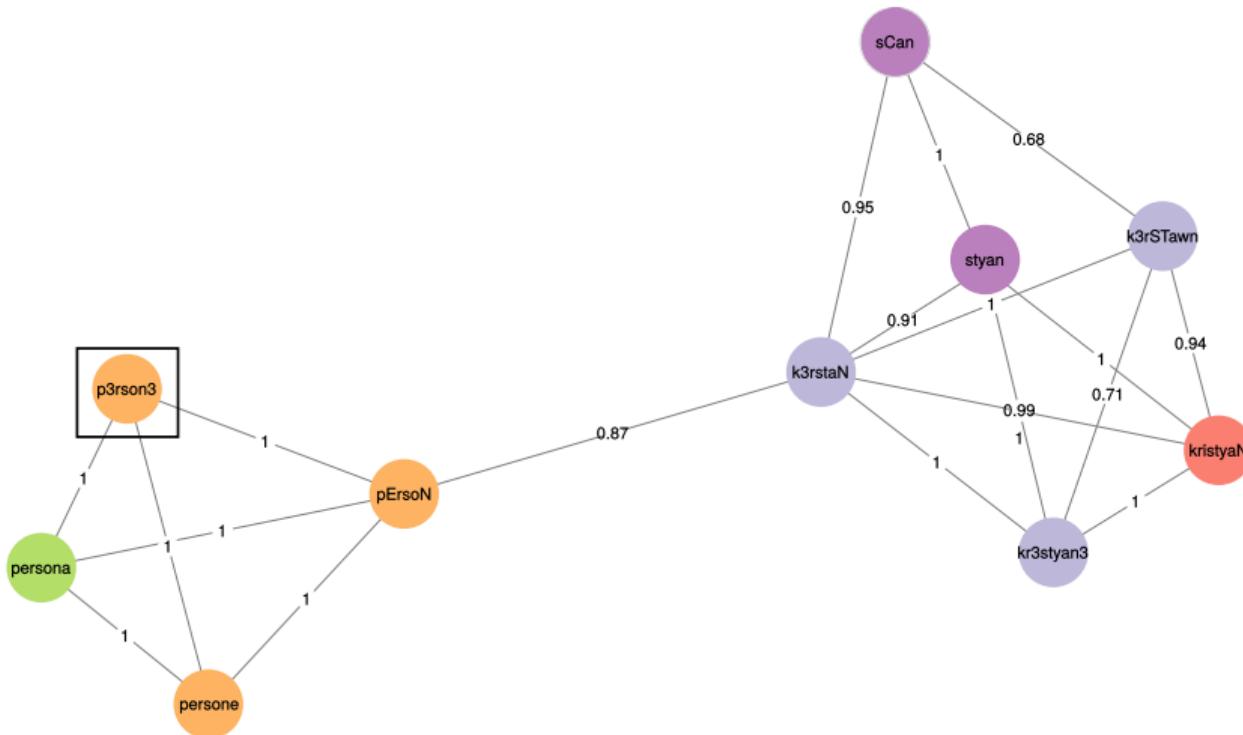
# Clustering via Label Propagation



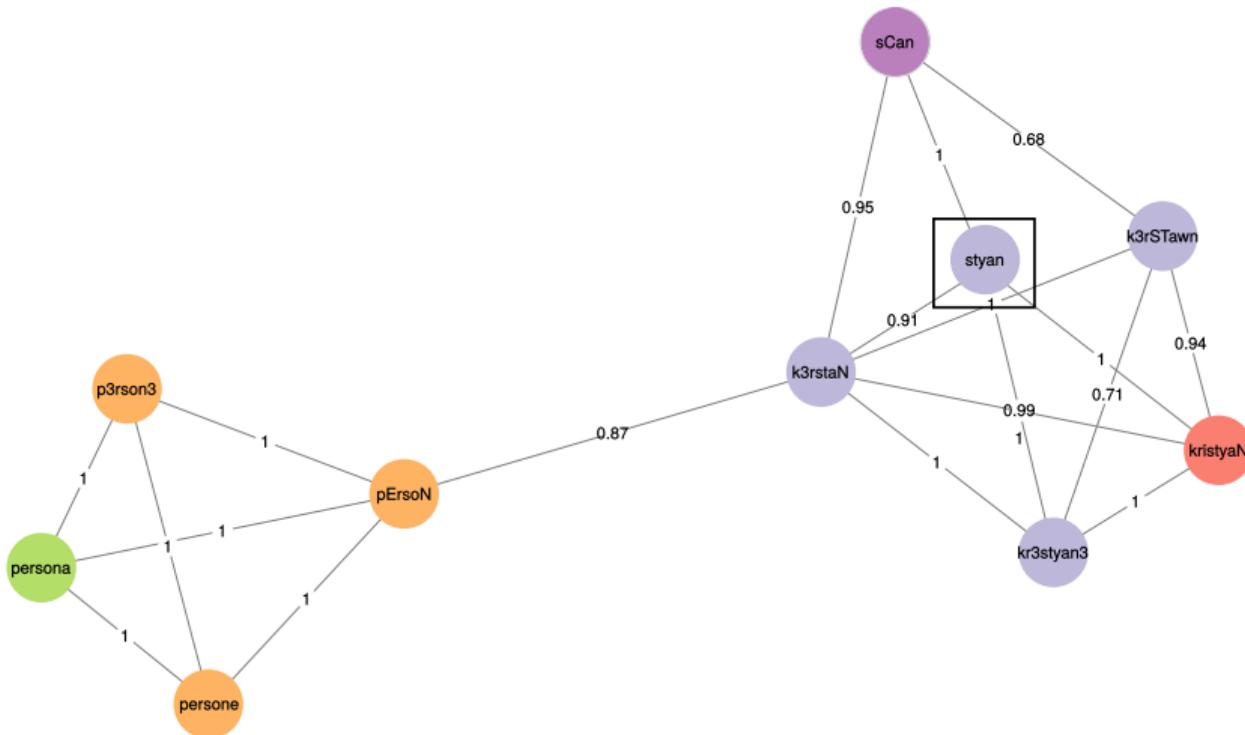
# Clustering via Label Propagation



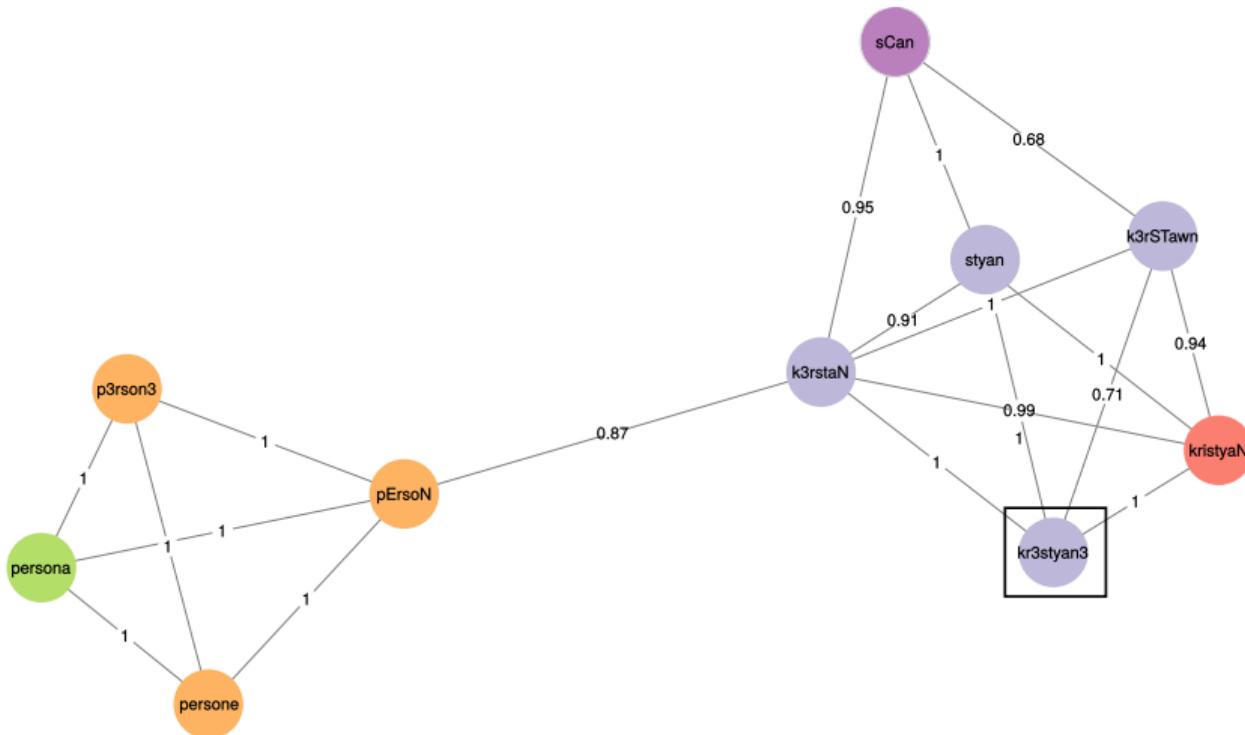
# Clustering via Label Propagation



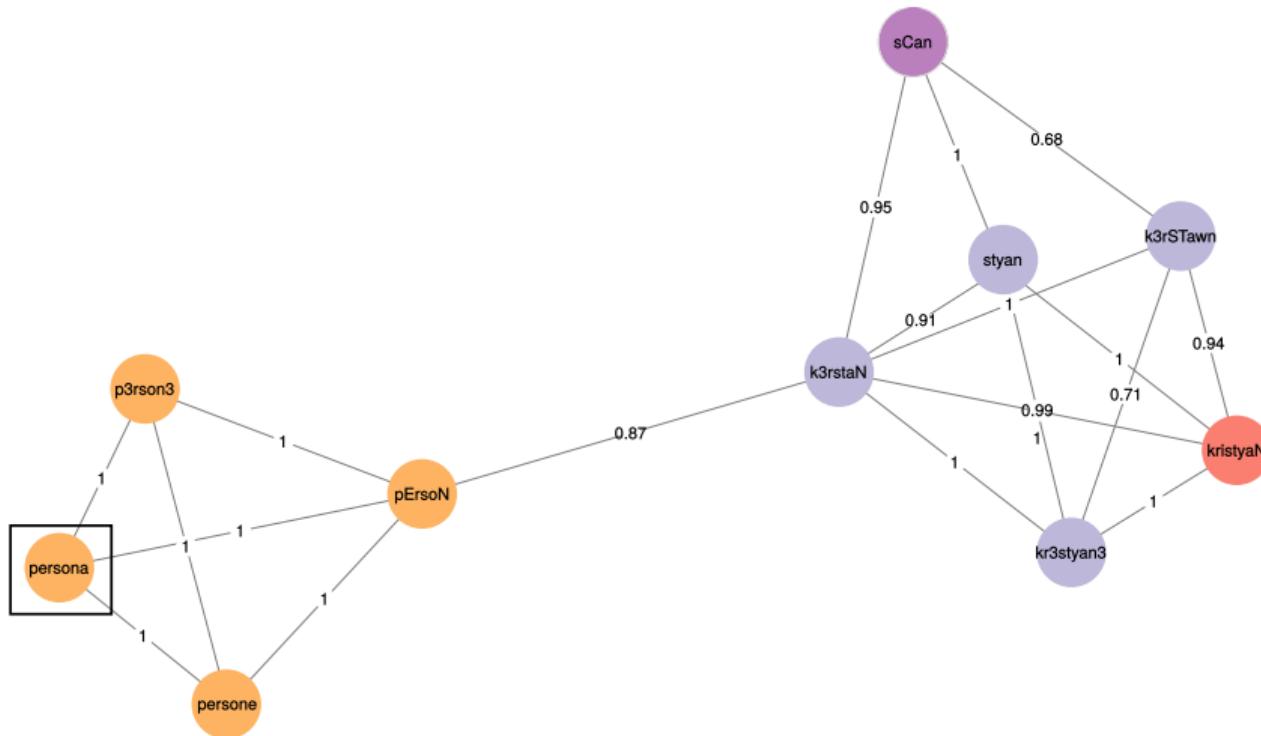
# Clustering via Label Propagation



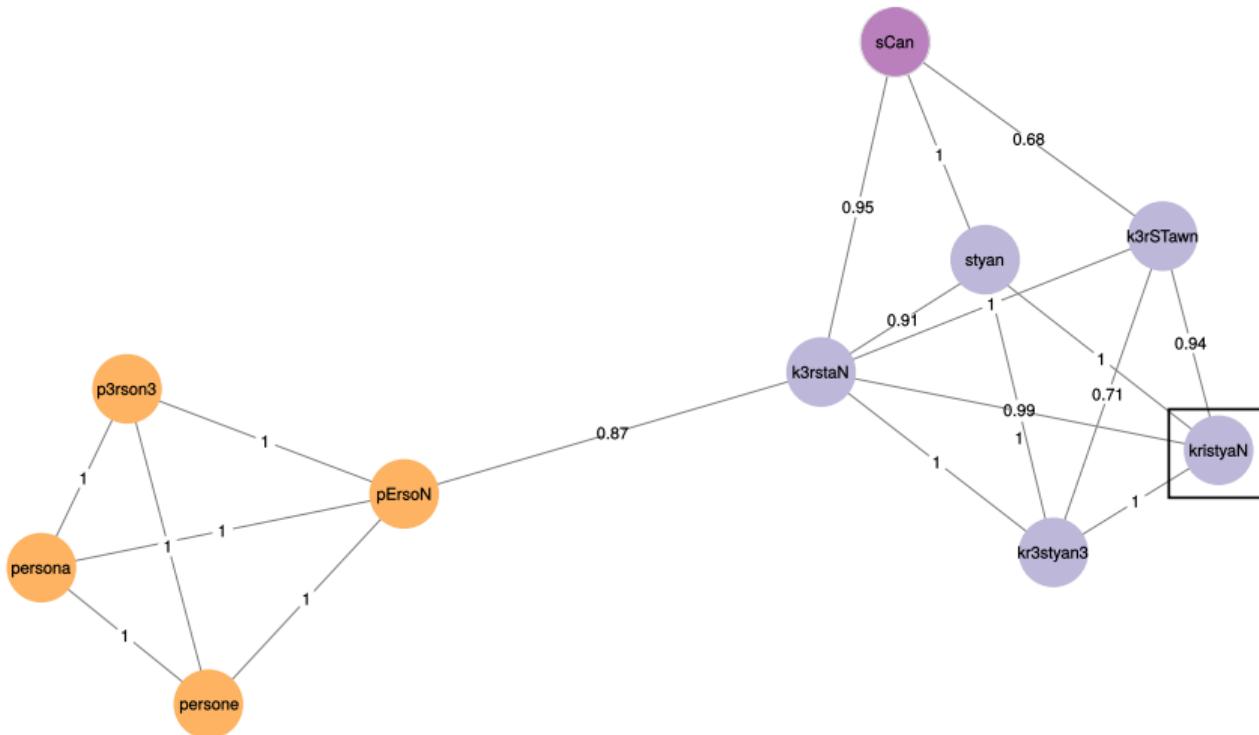
# Clustering via Label Propagation



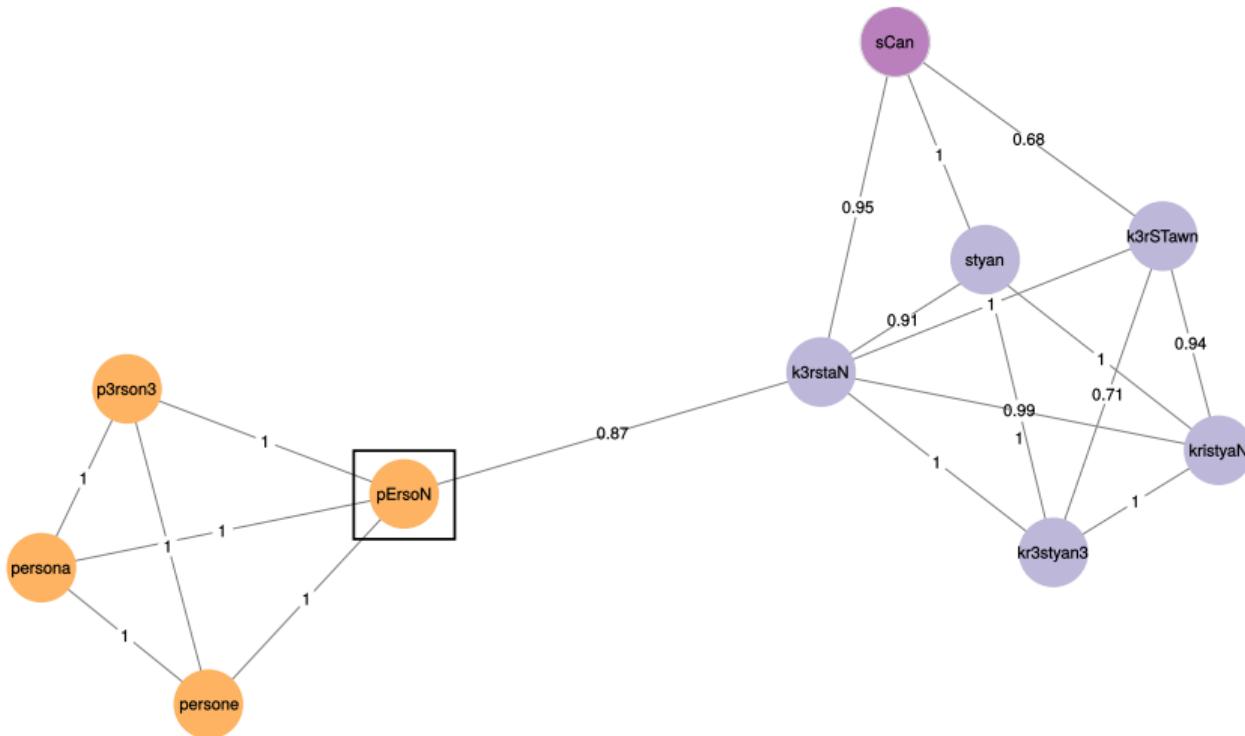
# Clustering via Label Propagation



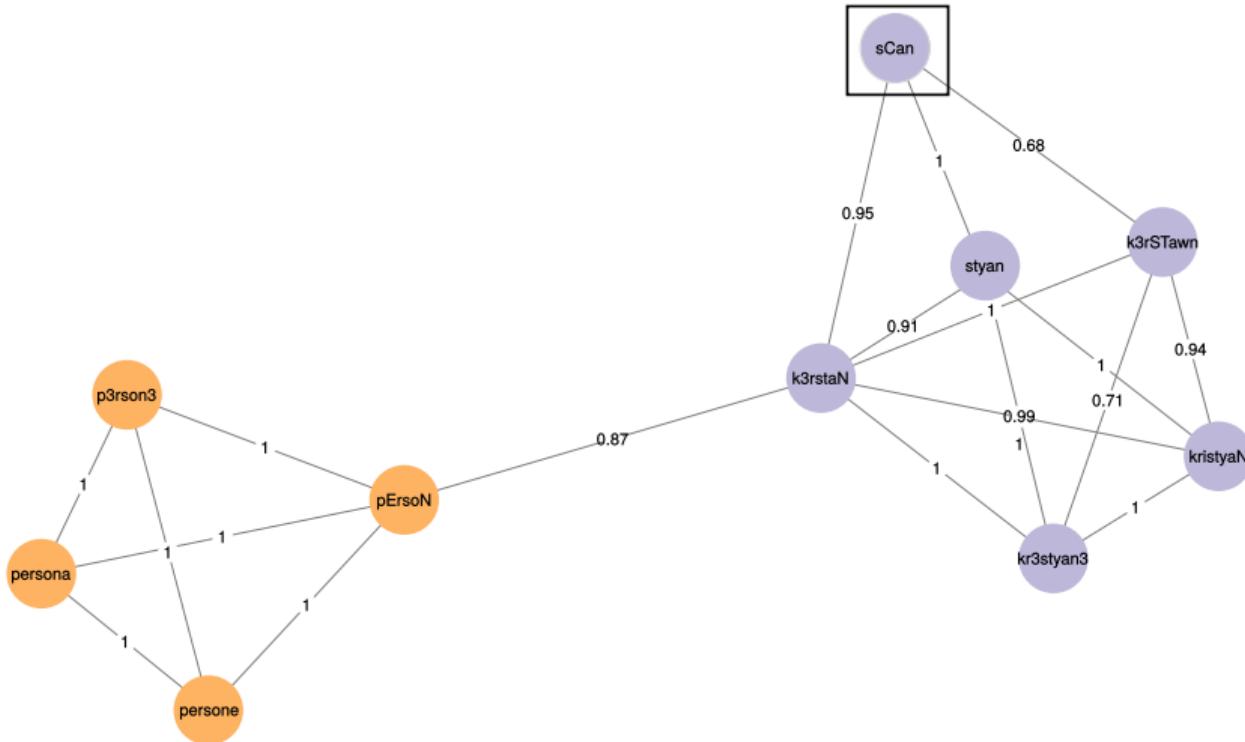
# Clustering via Label Propagation



# Clustering via Label Propagation



# Clustering via Label Propagation



# Cognate clustering

doculect	word	class label
ALBANIAN	vet3	0
ALBANIAN_TOSK	vEt3	0
ARAGONESE	ombre	1
ITALIAN_GROSSETO_TUSCAN	omo	2
ROMANIAN_MEGLENO	wom	2
VLACH	omu	2
ASTURIAN	persona	3
BALEAR_CATALAN	p3rson3	3
CATALAN	p3rson3	3
FRIULIAN	pErsoN	3
ITALIAN	persona	3
SPANISH	persona	3
VALENCIAN	persone	3
CORSICAN	nimu	4
DALMATIAN	om	5
EMILIANO_CARPIGIANO	om	5
ROMANIAN_2	om	5
TURIA_AROMANIAN	om	5
EMILIANO_FERRARESE	styan	6
LIGURIAN_STELLA	kristyan	6
NEAPOLITAN_CALABRESE	kr3styan3	6
ROMAGNOL_RAVENNATE	sCan	6
ROMANSH_GRISHUN	k3rStawn	6
ROMANSH_SURMIRAN	k3rstaN	6
GALICIAN	ome	7
GASCON	omi	7
PIEMONTESE_VERCELLESE	omaN	8
ROMANSH_VALLADER	uman	8
ALBANIAN_GHEG	Seri	9
SARDINIAN_CAMPIDANESE	omini	9
SARDINIAN_LOGUDARESE	omine	9

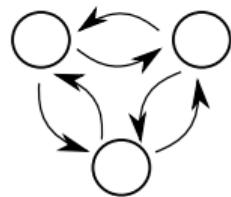
# Cognate clustering

concept	doclect	glot_fam	transcription
eye	DORASQUE	Chibchan	oko
eye	NORTHERN_LOW_SAXON	Indo-European	ok
eye	NORTH_FRISIAN_AMRUM	Indo-European	uk
eye	STELLINGWERFS	Indo-European	ok
eye	ASSAMESE	Indo-European	soku
eye	CHAKMA_UnnamedInSource	Indo-European	sog
eye	DALMATIAN	Indo-European	valko
eye	FRIULIAN	Indo-European	voli
eye	ITALIAN	Indo-European	okkyo
eye	ITALIAN_GROSSETO_TUSCAN	Indo-European	okyo
eye	JUDEO_ESPAGNOL	Indo-European	oxo
eye	LATIN	Indo-European	okulus
eye	NEAPOLITAN_CALABRESE	Indo-European	woky3
eye	ROMANIAN_2	Indo-European	oky
eye	ROMANIAN_MEGLENO	Indo-European	wokLu
eye	SARDINIAN	Indo-European	ogu
eye	SARDINIAN_CAMPIDANESE	Indo-European	oxu
eye	SARDINIAN_LOGUDARESE	Indo-European	okru
eye	SICILIAN_UnnamedInSource	Indo-European	okiu
eye	SPANISH	Indo-European	oho
eye	TURIA_AROMANIAN	Indo-European	okLu
eye	VLACH	Indo-European	oklku
eye	BELARUSIAN	Indo-European	voka
eye	BOSNIAN	Indo-European	oko
eye	BULGARIAN	Indo-European	oko
eye	CROATIAN	Indo-European	oko
eye	CZECH	Indo-European	oko
eye	KASHUBIAN	Indo-European	wakwo
eye	LOWER_SORBIAN	Indo-European	voka
eye	LOWER_SORBIAN_2	Indo-European	woko
eye	MACEDONIAN	Indo-European	oko
eye	OLD_CHURCH_SLAVONIC	Indo-European	oko
eye	POLISH	Indo-European	oko
eye	SERBOCROATIAN	Indo-European	oko
eye	SLOVAK	Indo-European	oko
eye	SLOVENIAN	Indo-European	oko
eye	UKRAINIAN	Indo-European	oko
eye	UPPER_SORBIAN	Indo-European	voCko
eye	UPPER_SORBIAN	Indo-European	voka
eye	BAINOUK_GUNYAMOLO	Atlantic-Congo	gili
eye	USINO	Nuclear_Trans_New_Guinea	ogo

# Phylogenetic inference

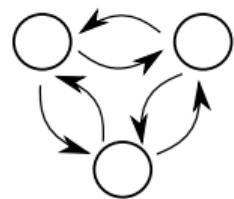
# Modeling language change

Markov process



# Modeling language change

Markov process

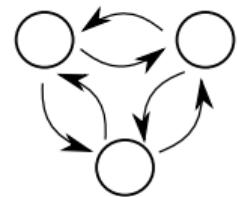


Phylogeny



# Modeling language change

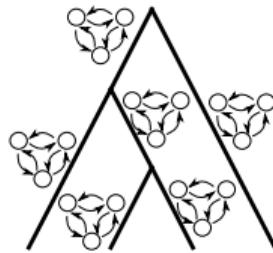
Markov process



Phylogeny

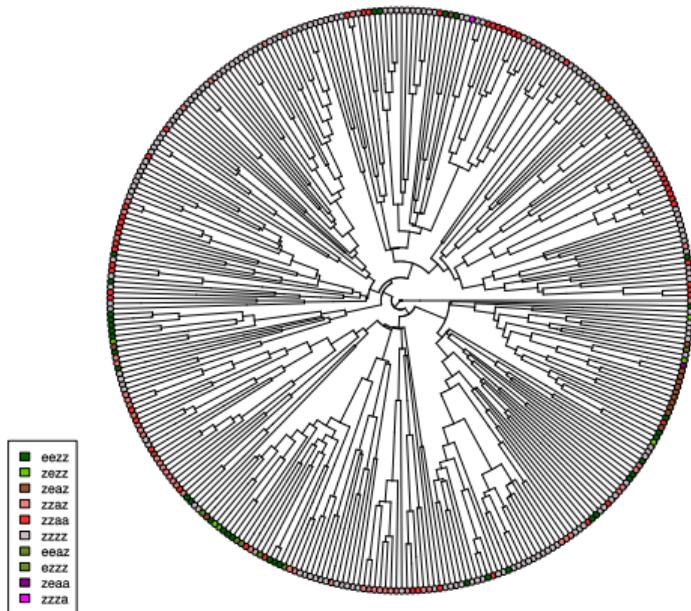


Branching process



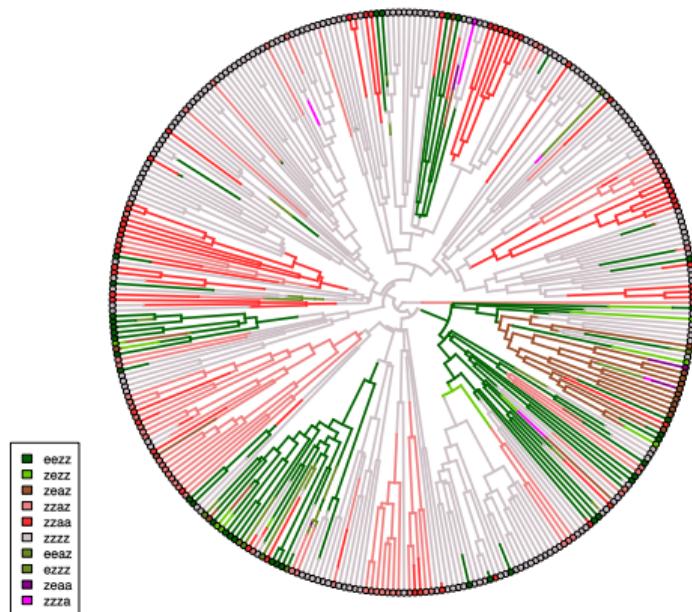
# Estimating rates of change

- if phylogeny and states of extant languages are known...



# Estimating rates of change

- if phylogeny and states of extant languages are known...
- ... transition rates and ancestral states can be estimated based on Markov model



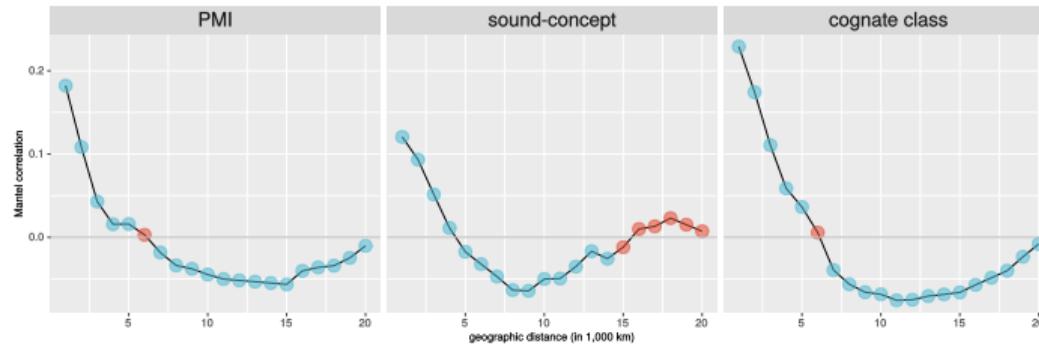
# ASJP word lists → character matrix

## ① Automatically inferred cognate classes

- each cluster  $cc$  defines one character
- doculect  $l$  has value 1 if its word list contains an element of  $cc$ , undefined if the slot of the corresponding concept is undefined, and 0 else

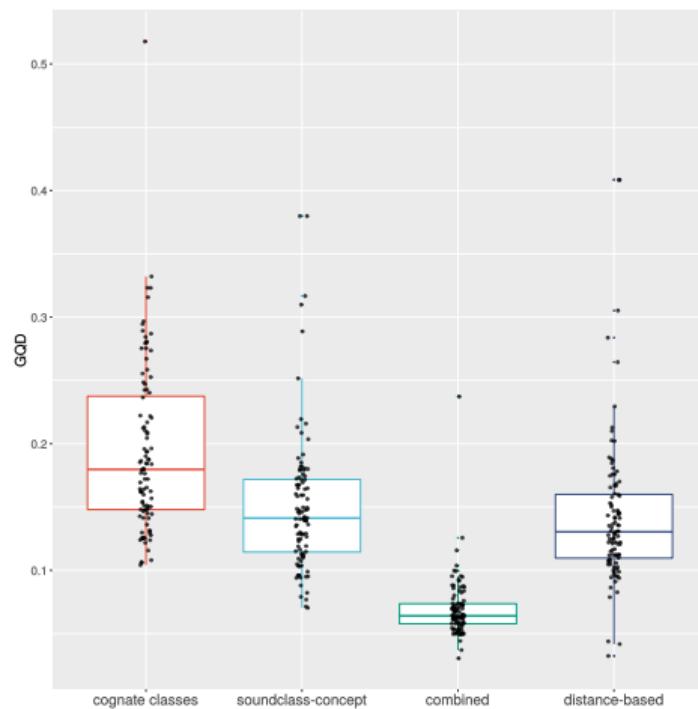
## ② Soundclass-concept characters

- each combination  $(c, s)$  of an ASJP concept  $c$  and an ASJP sound class  $s$  is a character
- doculect  $l$  has value 1 if one of its entries for  $c$  contains  $s$ , 0 if not, and undefined if there is no entry for  $c$



# Character matrix → trees

- validation
  - correlation with geographic distance
  - phylogenetic inference (Maximum Likelihood) + comparison to Glottolog expert tree on 100 random sample of ASJP doculects, containing between 20 and 400 doculects
  - using Stamatakis' **RAXML** (which is great)
- partitioned character-based inference seems to work best

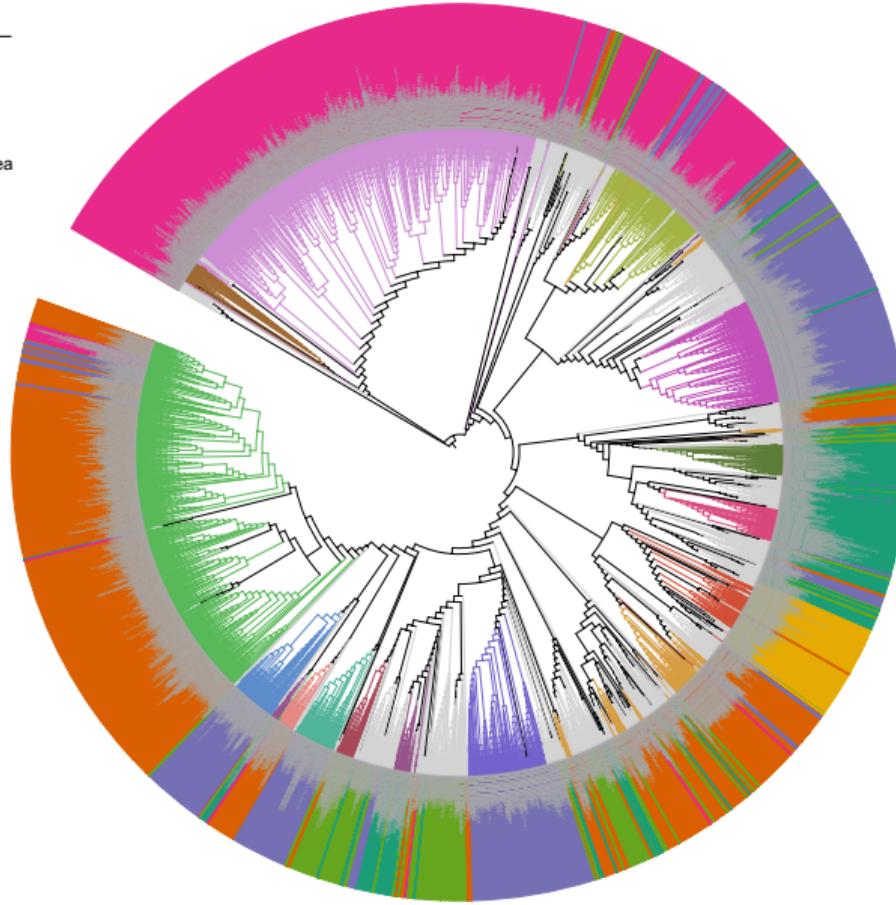


# The world tree

## Glottolog family

- Atlantic-Congo
- Mande
- Afro-Asiatic
- Nuclear\_Trans\_New\_Guinea
- Pama-Nyungan
- Timor-Alor-Pantar
- Otomanguean
- Indo-European
- Uto-Aztecan
- Tai-Kadai
- Mayan
- Austronesian
- Austroasiatic
- Sino-Tibetan
- Quechuan

- ## Macro-Area
- Africa
  - Papunesia
  - Eurasia
  - South America
  - North America
  - Australia



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